# AN EFFICIENT FAMILY OF RATIO TYPE ESTIMATORS FOR SIMPLE RANDOM SAMPLING 

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#### Abstract

The study provides an enhanced estimation of the population mean using known information on an auxiliary variable. An enhanced class of estimators is suggested for the same. The proposed estimator's bias and mean squared error (MSE) are calculated up to the first order of approximation. The optimum values of the characterizing constants are obtained by minimizing the MSE of the proposed estimator. The minimum MSE and the bias values are achieved by optimising the characterizing scalar. The MSE of the proposed estimator has also been compared both conceptually and empirically with the MSEs of competing estimators. Real and simulated data sets are adopted to verify the theoretical prerequisites for the proposed estimator's greater efficiency over competing estimators. The most efficient estimator is recommended for practical utility in different areas of applications and the suggested estimator filfills the requirement.


Keywords: Main variable; auxiliary variable; bias; mean square error; simple random sampling.

## 1. INTRODUCTION

Whenever there is a large population, it is natural and cost-effective to estimate population parameters using appropriate sampling techniques. Survey sampling is widely used in, demography, education, agriculture, business management, economics, engineering, industry, medical sciences, political science, social sciences, and a variety of other fields. The primary goal of sample survey theory is to draw conclusions based on unknown population parameters such as the total population, the proportion of the population, the mean of the population $\bar{Y}$ and the variance of the population $\sigma_{y}^{2}$ etc. For example, to estimate the $\bar{Y}$, sample mean is the most appropriate estimator for the estimation of population mean. Although the sample mean is an unbiased estimator of population mean, it has a significant amount of sampling variation, hence, the estimator of the parameter under study which satisfies some properties like unbiasedness, minimum variance etc. is preferred. One of the most active research areas in survey sampling is improving the efficiency of ratio, product, and regression estimators in the presence of known auxiliary data when estimating unknown population parameters for the study variable using various sample techniques. The use of auxiliary variable fulfills the requirement of searching such estimators. Sometimes in sample surveys, information on auxiliary variable X which is correlated with the main variable Y is also collected. Auxiliary information is supplied by the auxiliary variable and is collected on some additional cost of the survey. Auxiliary variable is highly negatively or positively correlated with the main variable and by the use of the auxiliary variable; the efficiency of the estimator

[^0]is improved. Using efficient estimator, we can reduce the sampling error presented in sampling technique. Sample being a part of population, leads to sampling error which cannot be eliminated but can be minimized by using efficient estimators.

Watson [1] proposed the usual regression estimator by using highly correlated X with Y. This estimator is a biased estimator and has lesser MSE than the sample mean estimator ( $\overline{\mathrm{y}}$ ). Cochran [2] proposed the usual ratio estimator of $\overline{\mathrm{Y}}$ by using a positively correlated X with Y. It is a biased estimator, but it has a lower MSE than $\overline{\mathrm{y}}$ estimator. Goodman [3] modified the usual ratio estimators so that the obtained ratio-type estimator is unbiased for the simple random sampling scheme. Chakrabarty [4] developed some ratio estimators that are more efficient than the traditional ratio estimator for estimating $\bar{Y}$, up to the first order of approximation with optimum conditions. Sahai and Ray [5] presented two families of ratio-type and product-type estimators based on simple random samples for a finite $\overline{\mathrm{Y}}$. Sisodia and Dwivedi [6] utilized the population coefficient of variation of study and auxiliary variables and suggested an estimator of $\overline{\mathrm{Y}}$. Using positively and negatively correlated auxiliary variables, Bahl and Tuteja [7] proposed exponential ratio-type and product-type estimators for $\bar{Y}$. Upadhyaya and Singh [8] estimated the $\overline{\mathrm{Y}}$ using a transformed X and proposed some ratio and product type estimators of $\bar{Y}$ by using coefficient of variation and the coefficient of kurtosis of X. Kadilar and Cingi [9] investigated the chain ratio-type estimator and obtained its MSE equation, demonstrating that under certain conditions, the chain ratio-type estimator is more efficient than the existing ratio estimator. Singh [10] used the product method of estimation, that includes simple linear transformations with known coefficients of X , to estimate a finite $\overline{\mathrm{Y}}$. The transformations provided efficient product estimators with less absolute bias than conventional product and other product type estimators. Singh et al. [11] introduced a modified ratio estimator that improved the efficiency of the ratio estimator using the prior value of the coefficient of kurtosis of X. He obtained and compared first order large sample approximations to the bias and MSE of the proposed estimator and compared with the sample mean and usual ratio type estimator. They also introduced the generalized version of the introduced variable. Singh and Tailor [12], worked on the improved ratio-cum-product estimators of $\overline{\mathrm{Y}}$. Kadilar and Cingi [13] adjusted the estimators in Upadhyaya and Singh [8] to the estimator in Singh and Tailor [14] and presented a class of ratio estimators for the estimate of $\bar{Y}$. Koshnevisan et al. [15] proposed a general family of estimators for estimating the $\overline{\mathrm{Y}}$ using known values of particular population parameters. Al-Omari et al. [16] introduced modified ratio estimators of the $\overline{\mathrm{Y}}$ involving the first or third quartiles of X correlated with Y . Yan and Tian [17] utilized the given skewness coefficient of X and developed certain ratio-type estimators for $\overline{\mathrm{Y}}$. The proposed estimator is more efficient than the traditional ratio estimator under some conditions. Pandey et al. [18] developed the estimator utilizing known auxiliary parameters. Subramani and Kumarpandiyan [19] mentioned a class of modified ratio estimators for estimating $\bar{Y}$ using a linear combination of the auxiliary variable's Coefficient of Variation and Median. They have also determined the conditions under which the proposed estimators outperform the existing modified ratio estimators. Jeelani and Maqbool [20] proposed an improved ratio type estimator of $\bar{Y}$ relying on skewness coefficient and quartile difference of X. Swain [21] suggested an alternative ratio type exponential estimator and compared with Bahl and Tuteja's ratio type exponential estimator and classical ratio estimator as regards bias and MSE with large sample approximations. Jerajuddin and Kishun [22] defined a modified ratio estimator for estimating $\overline{\mathrm{Y}}$ using the sample size, which was drawn from the population using SRSWOR. The bias, MSE, and percent relative efficiencies of existing and proposed estimators are computed and compared to justify the superiority of the proposed estimator over the discussed estimators. Soponviwatkul and Lawson [23] proposed new ratio estimators for estimating $\overline{\mathrm{Y}}$ based on known X . To estimate $\overline{\mathrm{Y}}$, they used a known population coefficient
of variation of X , a correlation coefficient between Y and X , and a sample regression coefficient.The bias and MSE expressions for the proposed estimators up to the first order of approximation have been obtained. The performance of the proposed estimators is compared to existing estimators. Ijaz and Ali [24] presented an efficient estimator for estimating $\overline{\mathrm{Y}}$ using SRS scheme. They developed a revised ratio estimator with the same efficiency as a regression estimator. On the other hand, it is a well-known fact that the linear regression estimator is more efficient than the majority of ratio estimators. They found the Bias and MSE up to the first order of approximation and explained the conditions under which the proposed estimators perform better than other estimators. Yadav et al. [25] investigated the improved estimation of peppermint average production at the block level in the Barabanki district of Uttar Pradesh State (India) and suggested certain estimators for $\bar{Y}$. As a main variable, population refers to the production population, and auxiliary-variable refers to the area of field. They investigated the sampling properties of estimators, such as bias and MSE, and compared the estimates to others in the literature. They conducted a numerical study for the natural population based on primary data collected from Banikodar Block of Barabanki District in Uttar Pradesh State to support the theoretical findings. Under SRS scheme, Yadav and Baghel [26] suggested a technique for estimating $\overline{\mathrm{Y}}$ using information pertaining to auxiliary parameters. They introduced a new class of $\bar{Y}$ estimators, as well as the class's Bias and MSE, which are deduced up to the first order of approximation. Yadav and Baghel [27] advocated for improved $\overline{\mathrm{Y}}$ estimation using a new class of estimators that use known information on X under simple random sampling. The members of the existing $\overline{\mathrm{Y}}$ estimators have been shown. The objective of the study is to search for a more efficient estimator of $\bar{Y}$ than the existing competing estimators by using some known auxiliary parameters. The suggested class's bias and MSE are calculated up to the first approximation order. The notations and the formulae are presented in Tables 1 and 2, respectively.

Table 1. Notations.

| N : Population Size | $\beta_{2}$ : Coefficient of Kurtosis of X |
| :---: | :---: |
| n: Sample Size | $\mathrm{Q}_{\mathrm{r}(\mathrm{x})}$ : Quartile range |
| f: Sampling Fraction | $\mathrm{Q}_{1(\mathrm{x})}$ : First Quartile of X |
| ${ }^{\mathrm{N}} \mathrm{Cn}$ : All possible samples of size n | $\mathrm{Q}_{3(\mathrm{x})}$ : Third Quartile of X |
| Y: Study variable | $\mathrm{Q}_{\mathrm{a}(\mathrm{x})}$ : Quartile Average |
| X: Auxiliary variable | QD: Quartile Deviation |
| $\mathrm{M}_{\mathrm{y}}$ : Median of the Y | TM: Tri Mean |
| $\mathrm{M}_{\mathrm{x}}$ :Median of the X | Bias( $\cdot$ : : Bias of the estimator |
| $\overline{\mathrm{Y}}$ : Population mean of Y | $\mathrm{V}(\cdot)$ : Variance of the estimator |
| $\overline{\mathrm{X}}$ : Population mean of X | MSE( $\cdot$ ):Mean squared error of the estimator |
| $\overline{\mathrm{y}}$ : Sample mean of Y | $\mathrm{C}_{\mathrm{y}}$ : Coefficient of variation of y |
| $\overline{\mathrm{x}}$ :Sample mean of X | $\mathrm{C}_{\mathrm{x}}$ :Coefficient of variation of $x$ |
| $\rho$ : Correlation coefficient between X and Y | $\mathrm{S}_{\mathrm{y}}{ }^{2}$ : PopulationMean Square of y |
| $\beta$ : Regression coefficient of Y on X | $\mathrm{S}_{\mathrm{x}}{ }^{2}$ : PopulationMean Square of x |
| $\beta_{1}$ : Coefficient of Skewness of X | $\mathrm{S}_{\mathrm{yx}}$ : Covariance between X and Y |

Table 2. Formulae.

| $\mathrm{f}=\frac{\mathrm{n}}{\mathrm{N}}$ | $\mathrm{S}_{\mathrm{x}}{ }^{2}=\frac{1}{\mathrm{~N}-1} \sum_{\mathrm{i}=1}^{\mathrm{n}}\left(\mathrm{X}_{\mathrm{i}}-\overline{\mathrm{X}}\right)^{2}$ |
| :--- | :--- |
| $\lambda=\frac{1-\mathrm{f}}{\mathrm{n}}$ | $\mathrm{V}(\overline{\mathrm{y}})=\lambda \overline{\mathrm{Y}}^{2} \mathrm{C}_{\mathrm{y}}{ }^{2}$ |


| $\bar{y}=\frac{1}{n} \sum_{i=1}^{n} y_{i}$ | $\mathrm{~V}(\overline{\mathrm{x}})=\lambda \overline{\mathrm{X}}^{2} \mathrm{C}_{\mathrm{x}}{ }^{2}$ |
| :--- | :--- |
| $\overline{\mathrm{x}}=\frac{1}{n} \sum_{i=1}^{n} \mathrm{x}_{\mathrm{i}}$ | $\rho=\frac{\mathrm{S}_{\mathrm{yx}}}{\mathrm{S}_{\mathrm{x}} \mathrm{S}_{\mathrm{y}}}$ |
| $\mathrm{C}_{\mathrm{y}}=\frac{\mathrm{S}_{\mathrm{y}}}{\overline{\mathrm{Y}}}$ | $\mathrm{QD}=\frac{\mathrm{Q}_{3}-\mathrm{Q}_{1}}{2}$ |
| $\mathrm{C}_{\mathrm{x}}=\frac{S_{\mathrm{x}}}{\overline{\mathrm{X}}}$ | $\mathrm{Q}_{\mathrm{a}(\mathrm{x})}=\frac{\mathrm{Q}_{1}+\mathrm{M}_{\mathrm{x}}+\mathrm{Q}_{3}}{3}$ |
| $\mathrm{~S}_{\mathrm{yx}}=\frac{1}{\mathrm{~N}-1} \sum_{i=1}^{\mathrm{n}}\left(\mathrm{Y}_{\mathrm{i}}-\overline{\mathrm{Y}}\right)\left(\mathrm{X}_{\mathrm{i}}-\overline{\mathrm{X}}\right)$ | $\mathrm{Q}_{\mathrm{r}(\mathrm{x})}=\mathrm{Q}_{3}-\mathrm{Q}_{1}$ |
| $\mathrm{~S}_{\mathrm{y}}{ }^{2}=\frac{1}{\mathrm{~N}-1} \sum_{\mathrm{i}=1}^{n}\left(\mathrm{Y}_{\mathrm{i}}-\overline{\mathrm{Y}}\right)^{2}$ | $\mathrm{TM}=\frac{\mathrm{Q}_{1}+2 \mathrm{M}_{\mathrm{x}}+\mathrm{Q}_{3}}{4}$ |

## 2. LITERATURE REVIEW OF EXISTING ESTIMATORS

To estimate the $\overline{\mathrm{Y}}$, sample mean is very suitable estimator because it possesses almost characteristics what the whole population is having. Sample mean which is an unbiased estimator of $\bar{Y}$ is given as,

$$
\mathrm{t}_{0}=\overline{\mathrm{y}}=\frac{1}{\mathrm{n}} \sum_{\mathrm{i}=1}^{\mathrm{n}} \mathrm{y}_{\mathrm{i}}
$$

with the variance,

$$
\mathrm{V}\left(\mathrm{t}_{0}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2} \mathrm{C}_{\mathrm{y}}^{2}
$$

Watson [1] described a technique for estimating the mean leaf area per leaf or per plant of a field crop. A large sampling is used to find the mean weight per leaf and on a small unit sample, the leaf area: leaf weight ratio and its regression on leaf weight are estimated. Alternative estimation methods based on the mean leaf weight and either unweights or weighted mean leaf area: leaf weight ratio is shown to provide positively biased estimates of mean leaf area. He suggested the estimator as,

$$
\mathrm{t}_{1}=\hat{\overline{\mathrm{Y}}}_{\mathrm{lr}}=\overline{\mathrm{y}}+\beta(\overline{\mathrm{X}}-\overline{\mathrm{x}})
$$

having the MSE,

$$
\operatorname{MSE}\left(\mathrm{t}_{1}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2} \mathrm{C}_{\mathrm{y}}^{2}\left(1-\rho^{2}\right)
$$

Cochran [2]was first to propose the classical ratio estimator of $\bar{Y}$ based on a positively correlated X and Y to enhance precision in estimating $\overline{\mathrm{Y}}$. The classical ratio estimator is given by,

$$
\mathrm{t}_{2}=\overline{\mathrm{y}}\left(\frac{\overline{\mathrm{x}}}{\overline{\mathrm{x}}}\right)
$$

The above estimator is a biased estimator of $\bar{Y}$ and its bias and MSE up to the first order of approximation are respectively,

$$
\operatorname{Bias}\left(\mathrm{t}_{2}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}\left(\mathrm{C}_{\mathrm{x}}^{2}-\rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right)
$$

$$
\operatorname{MSE}\left(\mathrm{t}_{2}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2}\left(\mathrm{C}_{\mathrm{y}}^{2}+\mathrm{C}_{\mathrm{x}}^{2}-2 \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right)
$$

Goodman [3] explained that when each unit in a population of N units has an x and y measurement and the population mean $\overline{\mathrm{X}}$ of X is known, the $\overline{\mathrm{Y}}$ is commonly estimated by taking a random sample of $n$ units and using one of the standard biased ratio-type estimators of $\overline{\mathrm{Y}}$, based on the ratio of $\bar{y}$ and $\overline{\mathrm{x}}$ along with the known and auxiliary parameters. He suggested the following estimator:

$$
t_{3}=\bar{X} \bar{r}
$$

The MSE of ratio-type estimators is,

$$
\operatorname{MSE}\left(\mathrm{t}_{3}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2}\left(\mathrm{C}_{\mathrm{y}}^{2}+\mathrm{C}_{\mathrm{x}}^{2}-2 \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right)
$$

Chakrabarty [4] mentioned that the precision of the regression estimator is usually higher than that of the ratio estimator, the ratio estimator is widely used in large-scale sample surveys due to its simplicity. In this research, he developed some ratio-type estimators that are more efficient than the traditional ratio estimator. The developed estimator for estimating $\overline{\mathrm{Y}} u \mathrm{p}$ to the first order of approximation and under optimum conditions is given as,

$$
\mathrm{t}_{4}=(1-\alpha) \overline{\mathrm{y}}+\alpha \overline{\mathrm{y}}\left(\frac{\overline{\mathrm{X}}}{\overline{\bar{x}}}\right)
$$

The bias and MSE of the developed estimator are respectively,

$$
\begin{gathered}
\operatorname{Bias}\left(\mathrm{t}_{4}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}\left(\frac{\alpha}{2} \mathrm{C}_{\mathrm{x}}{ }^{2}-\alpha \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right) \\
\operatorname{MSE}\left(\mathrm{t}_{4}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2}\left(\mathrm{C}_{\mathrm{y}}{ }^{2}+\alpha^{2} \mathrm{C}_{\mathrm{x}}{ }^{2}-2 \alpha \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right)
\end{gathered}
$$

where, $\alpha=\rho \frac{C_{y}}{C_{\mathrm{x}}}$ which minimizes the $\operatorname{MSE}\left(\mathrm{t}_{4}\right)$.
Sahai and Ray [5] presented families of ratio-type for a finite $\overline{\mathrm{Y}}$ based on simple random samples of observations on the variable of interest and an associated variable.

$$
\mathrm{t}_{5}=\overline{\mathrm{y}}\left\{2-\left(\frac{\overline{\mathrm{x}}}{\overline{\mathrm{x}}}\right)^{\mathrm{w}}\right\}
$$

Using some prior knowledge, he has demonstrated that the families contain estimators with lower MSE in application than the standard ratio and sample mean estimators.

$$
\begin{aligned}
& \operatorname{Bias}\left(\mathrm{t}_{5}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}\left(-\frac{\omega(1-\omega)}{2} \mathrm{C}_{\mathrm{x}}^{2}-\omega \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right) \\
& \operatorname{MSE}\left(\mathrm{t}_{5}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \bar{Y}^{2}\left(\mathrm{C}_{\mathrm{y}}^{2}+\omega^{2} \mathrm{C}_{\mathrm{x}}^{2}-2 \omega \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right)
\end{aligned}
$$

where, $\omega=\rho \frac{\mathrm{C}_{\mathrm{y}}}{\mathrm{C}_{\mathrm{x}}}$ which minimizes the $\operatorname{MSE}\left(\mathrm{t}_{5}\right)$.
Sisodia and Dwivedi [6] have proposed a modified ratio type estimator for $\overline{\mathrm{Y}}$ by making use of coefficient of variation of X . The modified estimator is,

$$
t_{6}=\bar{y}\left(\frac{\bar{x}+C_{x}}{\bar{x}+C_{x}}\right)
$$

The bias and MSE of the given modified estimator are respectively,

$$
\begin{gathered}
\operatorname{Bias}\left(\mathrm{t}_{6}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}\left(\mathrm{R}_{6}{ }^{2} \mathrm{C}_{\mathrm{x}}{ }^{2}-\mathrm{R}_{6} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right) \\
\operatorname{MSE}\left(\mathrm{t}_{6}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2}\left(\mathrm{C}_{\mathrm{y}}{ }^{2}+\mathrm{R}_{6}{ }^{2} \mathrm{C}_{\mathrm{x}}{ }^{2}-2 \mathrm{R}_{6} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right)
\end{gathered}
$$

where, $\mathrm{R}_{6}=\frac{\overline{\mathrm{x}}}{\overline{\mathrm{X}}+\mathrm{C}_{\mathrm{x}}}$.
Bahl and Tuteja [7] suggested a new ratio and product type estimator for estimating $\bar{Y}$ using a single X . These estimators are shown to be more efficient in practical situations when compared to traditional mean per unit, ratio, and product estimators. The suggested estimator is,

$$
t_{7}=\bar{y} \exp \left(\frac{\bar{x}-\bar{x}}{\bar{x}+\bar{x}}\right)
$$

The bias and mean square error of these estimators were obtained and given respectively,

$$
\begin{gathered}
\operatorname{Bias}\left(\mathrm{t}_{7}\right)=\frac{1-\mathrm{f}}{8 \mathrm{n}} \overline{\mathrm{Y}}\left(3 \mathrm{C}_{\mathrm{x}}^{2}-4 \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right) \\
\operatorname{MSE}\left(\mathrm{t}_{7}\right)=\frac{1-\mathrm{f}^{2}}{\mathrm{n}} \overline{\mathrm{Y}}^{2}\left(\mathrm{C}_{\mathrm{y}}{ }^{2}+\frac{\mathrm{C}_{\mathrm{x}}{ }^{2}}{4}-\rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right)
\end{gathered}
$$

Upadhyaya and Singh [8] defined a transformed $X$ to estimate the finite $\bar{Y}$ and proposed the estimator of $\bar{Y}$ using coefficient of variation and coefficient of kurtosis of $X$ as,

$$
\mathrm{t}_{8}=\overline{\mathrm{y}} \exp \left(\frac{\overline{\mathrm{X}} \beta_{2}-\mathrm{C}_{\mathrm{x}}}{\overline{\mathrm{x}} \beta_{2}+\mathrm{C}_{\mathrm{x}}}\right)
$$

The bias and MSE of the proposed estimator have been obtained and are given respectively,

$$
\begin{gathered}
\operatorname{Bias}\left(\mathrm{t}_{8}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}\left(\mathrm{R}_{8}{ }^{2} \mathrm{C}_{\mathrm{x}}{ }^{2}-\mathrm{R}_{8} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right) \\
\operatorname{MSE}\left(\mathrm{t}_{8}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2}\left(\mathrm{C}_{\mathrm{y}}{ }^{2}+\mathrm{R}_{8}{ }^{2} \mathrm{C}_{\mathrm{x}}{ }^{2}-2 \mathrm{R}_{8} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right)
\end{gathered}
$$

where, $R_{8}=\frac{\overline{\mathrm{x}} \beta_{2}}{\overline{\mathrm{x}} \boldsymbol{\beta}_{2}+\mathrm{C}_{\mathrm{x}}}$.
Kadilar and Cingi [9] proposed the chain ratio-type estimator and shown that, under certain conditions, the chain ratio-type estimator is more efficient than the traditional ratio estimator. The chain ratio-type estimator is given as,

$$
\mathrm{t}_{9}=\overline{\mathrm{y}}\left(\frac{\overline{\mathrm{X}}^{2}}{\overline{\mathrm{x}}^{2}}\right)
$$

The calculated bias and MSE for the chain ratio-type estimator is as follows,

$$
\begin{gathered}
\operatorname{Bias}\left(\mathrm{t}_{9}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}\left(3 \mathrm{C}_{\mathrm{x}}^{2}-2 \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right) \\
\operatorname{MSE}\left(\mathrm{t}_{9}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2}\left(\mathrm{C}_{\mathrm{y}}^{2}+4 \mathrm{C}_{\mathrm{x}}^{2}-4 \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right)
\end{gathered}
$$

Singh [10] considered a simple linear transformation of the known coefficient of variables for estimating $\mathrm{a} \overline{\mathrm{Y}}$ with the Ratio method of estimation.

$$
\mathrm{t}_{10}=\overline{\mathrm{y}}\left(\frac{\overline{\mathrm{X}} \beta_{1}+\mathrm{S}_{\mathrm{x}}}{\overline{\mathrm{x}} \beta_{1}+\mathrm{S}_{\mathrm{x}}}\right)
$$

The suggested transformations provide efficient ratio estimators with less absolute bias than traditional ratio and other ratio type estimators. The bias and MSE of the suggested estimator are given as,

$$
\begin{gathered}
\operatorname{Bias}\left(\mathrm{t}_{10}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}\left(\mathrm{R}_{10}{ }^{2} \mathrm{C}_{\mathrm{x}}{ }^{2}-\mathrm{R}_{10} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right) \\
\operatorname{MSE}\left(\mathrm{t}_{10}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2}\left(\mathrm{C}_{\mathrm{y}}{ }^{2}+\mathrm{R}_{10}{ }^{2} \mathrm{C}_{\mathrm{x}}{ }^{2}-2 \mathrm{R}_{10} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right)
\end{gathered}
$$

where, $\mathrm{R}_{10}=\frac{\overline{\mathrm{x}} \beta_{1}}{\overline{\mathrm{X}} \beta_{2}+\mathrm{S}_{\mathrm{x}}}$.
Singh and Tailor [14] presented a modified ratio estimator using correlation coefficient to improve the efficiency of ratio estimator as,

$$
\mathrm{t}_{11}=\overline{\mathrm{y}}\left(\frac{\overline{\mathrm{x}}+\rho}{\overline{\mathrm{x}}+\rho}\right)
$$

The Bias and MSE of the above estimator respectively as,

$$
\begin{gathered}
\operatorname{Bias}\left(\mathrm{t}_{11}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}\left(\mathrm{R}_{11}{ }^{2} \mathrm{C}_{\mathrm{x}}{ }^{2}-\mathrm{R}_{11} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right) \\
\operatorname{MSE}\left(\mathrm{t}_{11}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2}\left(\mathrm{C}_{\mathrm{y}}{ }^{2}+\mathrm{R}_{11}{ }^{2} \mathrm{C}_{\mathrm{x}}{ }^{2}-2 \mathrm{R}_{11} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right)
\end{gathered}
$$

where, $\mathrm{R}_{11}=\frac{\overline{\mathrm{x}}}{\overline{\mathrm{x}}+\rho}$.
Singh et al. [11] proposed a modified ratio estimator that improved the efficiency of the ratio estimator by incorporating the prior value of the coefficient of kurtosis of X as,

$$
\mathrm{t}_{12}=\overline{\mathrm{y}}\left(\frac{\overline{\mathrm{x}}+\beta_{2}}{\overline{\mathrm{x}}+\beta_{2}}\right)
$$

The first order large sample approximations to the bias and MSE of the proposed estimator are obtained and given respectively as,

$$
\begin{gathered}
\operatorname{Bias}\left(\mathrm{t}_{12}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}\left(\mathrm{R}_{12}{ }^{2} \mathrm{C}_{\mathrm{x}}{ }^{2}-\mathrm{R}_{12} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right) \\
\operatorname{MSE}\left(\mathrm{t}_{12}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2}\left(\mathrm{C}_{\mathrm{y}}{ }^{2}+\mathrm{R}_{12}{ }^{2} \mathrm{C}_{\mathrm{x}}{ }^{2}-2 \mathrm{R}_{12} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right)
\end{gathered}
$$

where, $\mathrm{R}_{12}=\frac{\overline{\mathrm{X}}}{\overline{\mathrm{X}}+\beta_{2}}$.
Singh and Tailor [12] proposed the estimator of $\bar{Y} u s i n g$ coefficient of variation of X as,

$$
\mathrm{t}_{13}=\overline{\mathrm{y}}\left[\alpha\left(\frac{\overline{\mathrm{X}}+\mathrm{C}_{\mathrm{x}}}{\overline{\mathrm{x}}+\mathrm{C}_{\mathrm{x}}}\right)+(1-\alpha)\left(\frac{\overline{\mathrm{x}}+\mathrm{C}_{\mathrm{x}}}{\overline{\mathrm{X}}+\mathrm{C}_{\mathrm{x}}}\right)\right]
$$

The minimum MSE of the given estimator for $\alpha=\rho \frac{C_{y}}{C_{x}}$ is,

$$
\operatorname{MSE}\left(\mathrm{t}_{13}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2} \mathrm{C}_{\mathrm{y}}^{2}\left(1-\rho^{2}\right)
$$

Kadilar and Cingi [13] by adapting the estimators in Upadhyaya and Singh [8] and Singh and Tailor [14] proposed a class of ratio estimators for the estimate of $\bar{Y}$ as,

$$
\mathrm{t}_{14}=\frac{\overline{\mathrm{y}}}{\overline{\mathrm{x}} \mathrm{C}_{\mathrm{x}}+\rho}\left(\overline{\mathrm{X}} \mathrm{C}_{\mathrm{x}}+\rho\right)
$$

The Bias and MSE of the estimator are calculated up to first order of approximation is given as,

$$
\begin{gathered}
\operatorname{Bias}\left(\mathrm{t}_{14}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}\left(\mathrm{R}_{14}{ }^{2} \mathrm{C}_{\mathrm{x}}{ }^{2}-\mathrm{R}_{14} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right) \\
\operatorname{MSE}\left(\mathrm{t}_{14}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2}\left[\mathrm{C}_{\mathrm{y}}{ }^{2}+\mathrm{R}_{14}{ }^{2} \mathrm{C}_{\mathrm{x}}{ }^{2}-2 \mathrm{R}_{14} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right]
\end{gathered}
$$

where, $\mathrm{R}_{14}=\frac{\overline{\mathrm{X}} \mathrm{c}_{\mathrm{x}}}{\overline{\mathrm{X}} \mathrm{c}_{\mathrm{x}}+\rho}$.
Khoshnevisan et al. [15] proposed a general family of estimators for estimating the $\overline{\mathrm{Y}}$ using known values of particular auxiliary population parameters as,

$$
\mathrm{t}_{15}=\overline{\mathrm{y}}\left[\frac{\mathrm{a} \overline{\mathrm{X}}+\mathrm{b}}{\alpha^{\prime}(\mathrm{a} \overline{\mathrm{x}}+\mathrm{b})+\left(1-\alpha^{\prime}\right)(\mathrm{a} \overline{\mathrm{X}}+\mathrm{b})}\right]^{\mathrm{g}}
$$

Up to first order of approximation, bias and MSE expressions are generated,

$$
\operatorname{Bias}\left(\mathrm{t}_{15}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}\left[\frac{\mathrm{~g}(\mathrm{~g}+1)}{2} \alpha^{\prime 2} \mathrm{R}_{15}^{2} \mathrm{C}_{\mathrm{x}}^{2}-\alpha^{\prime} \mathrm{R}_{15}{\left.\mathrm{~g} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right]}\right.
$$

where, $\mathrm{R}_{14}=\frac{\mathrm{a} \overline{\mathrm{X}}}{\mathrm{a}+\mathrm{x}}$.
The minimum MSE for optimum $\alpha^{\prime}$ 'is,

$$
\operatorname{MSE}\left(\mathrm{t}_{15}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2} \mathrm{C}_{\mathrm{y}}^{2}\left(1-\rho^{2}\right)
$$

Al-Omari et al. [16] used the third quartiles of an auxiliary variable that is correlated with the variable of interest are suggested as modified ratio estimators of the $\bar{Y}$ of the variable of interest,

$$
\mathrm{t}_{16}=\overline{\mathrm{y}}\left(\frac{\overline{\mathrm{x}}+\mathrm{Q}_{3}}{\overline{\mathrm{x}}+\mathrm{Q}_{3}}\right)
$$

The calculated Bias and MSE for the estimator are given as,

$$
\operatorname{Bias}\left(\mathrm{t}_{16}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}\left(\mathrm{R}_{16}^{2} \mathrm{C}_{\mathrm{x}}^{2}-\mathrm{R}_{16} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right)
$$

$$
\operatorname{MSE}\left(\mathrm{t}_{16}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2}\left(\mathrm{C}_{\mathrm{y}}^{2}+\mathrm{R}_{16}{ }^{2} \mathrm{C}_{\mathrm{x}}^{2}-2 \mathrm{R}_{16} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right)
$$

where, $\mathrm{R}_{16}=\frac{\overline{\mathrm{X}}}{\overline{\mathrm{X}}+\mathrm{Q}_{3}}$.
Yan and Tian [17] used the known skewness coefficient of the auxiliary variable, and provided some ratio-type estimators for $\bar{Y}$

$$
\begin{aligned}
\mathrm{t}_{17} & =\overline{\mathrm{y}}\left(\frac{\overline{\mathrm{x}}+\beta_{1}}{\overline{\mathrm{x}}+\beta_{1}}\right) \\
\mathrm{t}_{18} & =\overline{\mathrm{y}}\left(\frac{\overline{\mathrm{x}} \beta_{1}+\beta_{2}}{\overline{\mathrm{x}} \beta_{1}+\beta_{2}}\right) \\
\mathrm{t}_{19} & =\overline{\mathrm{y}}\left(\frac{\overline{\mathrm{x}} \mathrm{C}_{\mathrm{x}}+\beta_{1}}{\overline{\mathrm{x}} C_{\mathrm{x}}+\beta_{1}}\right) \\
\mathrm{t}_{20} & =\overline{\mathrm{y}}\left(\frac{\overline{\mathrm{x}} \beta_{2}+\beta_{1}}{\overline{\mathrm{x}} \beta_{2}+\beta_{1}}\right)
\end{aligned}
$$

Theoretically, for all proposed ratio estimators, the expressions of MSE up to first order of approximation were produced, which are given as,

$$
\begin{gathered}
\operatorname{Bias}\left(\mathrm{t}_{17}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}\left(\mathrm{R}_{17}{ }^{2} \mathrm{C}_{\mathrm{x}}{ }^{2}-\mathrm{R}_{17} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right) \\
\operatorname{Bias}\left(\mathrm{t}_{18}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}\left(\mathrm{R}_{18}{ }^{2} \mathrm{C}_{\mathrm{x}}{ }^{2}-\mathrm{R}_{18} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right) \\
\operatorname{Bias}\left(\mathrm{t}_{19}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}\left(\mathrm{R}_{19}{ }^{2} \mathrm{C}_{\mathrm{x}}{ }^{2}-\mathrm{R}_{19} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right) \\
\operatorname{Bias}\left(\mathrm{t}_{20}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}\left(\mathrm{R}_{20}{ }^{2} \mathrm{C}_{\mathrm{x}}{ }^{2}-\mathrm{R}_{20} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right) \\
\operatorname{MSE}\left(\mathrm{t}_{17}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2}\left(\mathrm{C}_{\mathrm{y}}{ }^{2}+\mathrm{R}_{17}{ }^{2} \mathrm{C}_{\mathrm{x}}{ }^{2}-2 \mathrm{R}_{17} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right) \\
\operatorname{MSE}\left(\mathrm{t}_{18}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2}\left(\mathrm{C}_{\mathrm{y}}{ }^{2}+\mathrm{R}_{18}{ }^{2} \mathrm{C}_{\mathrm{x}}{ }^{2}-2 \mathrm{R}_{18} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right) \\
\operatorname{MSE}\left(\mathrm{t}_{19}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2}\left(\mathrm{C}_{\mathrm{y}}{ }^{2}+\mathrm{R}_{19}{ }^{2} \mathrm{C}_{\mathrm{x}}{ }^{2}-2 \mathrm{R}_{19} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right) \\
\operatorname{MSE}\left(\mathrm{t}_{20}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2}\left(\mathrm{C}_{\mathrm{y}}{ }^{2}+\mathrm{R}_{20}{ }^{2} \mathrm{C}_{\mathrm{x}}{ }^{2}-2 \mathrm{R}_{20} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right)
\end{gathered}
$$

where, $\mathrm{R}_{17}=\frac{\overline{\mathrm{X}}}{\overline{\mathrm{X}}+\beta_{1}}, \mathrm{R}_{18}=\frac{\overline{\mathrm{X}} \beta_{1}}{\overline{\mathrm{X}} \beta_{1}+\beta_{2}}, \mathrm{R}_{19}=\frac{\overline{\mathrm{X}} \mathrm{C}_{\mathrm{x}}}{\overline{\mathrm{X}} \mathrm{C}_{\mathrm{x}}+\beta_{1}}, \mathrm{R}_{20}=\frac{\overline{\mathrm{X}} \beta_{2}}{\overline{\mathrm{X}} \beta_{2}+\beta_{1}}$.
Pandey et al. [18] developed the estimator utilizing auxiliary information, which is given as,

$$
t_{21}=\bar{y} \frac{\bar{x}}{\bar{x}}\left(1-\frac{k \bar{x}^{2} \bar{x}^{3}}{n \bar{x}^{3}}\right)^{-1}
$$

The Bias and MSE are as follows,

$$
\begin{gathered}
\operatorname{Bias}\left(\mathrm{t}_{21}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}\left(\mathrm{kC}_{\mathrm{x}}^{2}-\rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right) \\
\operatorname{MSE}\left(\mathrm{t}_{21}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2}\left(\mathrm{C}_{\mathrm{y}}^{2}+\mathrm{k}^{2} \mathrm{C}_{\mathrm{x}}^{2}-2 \mathrm{k} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right)
\end{gathered}
$$

where, $\mathrm{k}=\rho \frac{\mathrm{C}_{\mathrm{y}}}{\mathrm{C}_{\mathrm{x}}}$.

Subramani and Kumarpandiyan [19] worked with a class of modified ratio estimators that use a linear combination of the known values of the Coefficient of Variation and the Median of X to estimate $\overline{\mathrm{Y}}$ as,

$$
\mathrm{t}_{22}=\overline{\mathrm{y}}\left(\frac{\overline{\mathrm{x}} \mathrm{C}_{\mathrm{x}}+\mathrm{M}_{\mathrm{x}}}{\overline{\mathrm{x}} \mathrm{C}_{\mathrm{x}}+\mathrm{M}_{\mathrm{x}}}\right)
$$

The proposed estimator's bias and MSE are calculated, which are,

$$
\begin{gathered}
\operatorname{Bias}\left(\mathrm{t}_{22}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}\left(\mathrm{R}_{22}{ }^{2} \mathrm{C}_{\mathrm{x}}{ }^{2}-\mathrm{R}_{22} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right) \\
\operatorname{MSE}\left(\mathrm{t}_{22}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2}\left(\mathrm{C}_{\mathrm{y}}{ }^{2}+\mathrm{R}_{22}{ }^{2} \mathrm{C}_{\mathrm{x}}{ }^{2}-2 \mathrm{R}_{22} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right)
\end{gathered}
$$

where, $\mathrm{k}=\frac{\overline{\mathrm{X}} \mathrm{c}_{\mathrm{x}}}{\overline{\mathrm{X}} \mathrm{C}_{\mathrm{x}}+\mathrm{M}_{\mathrm{x}}}$.
Jeelani and Maqbool [20] worked with the linear combination of known population values of coefficient of skewness and quartile deviation of $X$ to estimate $\bar{Y}$ as,

$$
t_{23}=\bar{y}\left(\frac{\bar{x} \beta_{1}+Q D}{\bar{x} \beta_{1}+Q D}\right)
$$

Up to the first degree of approximation, bias and MSE are calculated as,

$$
\begin{gathered}
\operatorname{Bias}\left(\mathrm{t}_{23}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}\left(\mathrm{R}_{23}{ }^{2} \mathrm{C}_{\mathrm{x}}^{2}-\mathrm{R}_{23} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right) \\
\operatorname{MSE}\left(\mathrm{t}_{23}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2}\left(\mathrm{C}_{\mathrm{y}}{ }^{2}+\mathrm{R}_{23}{ }^{2} \mathrm{C}_{\mathrm{x}}{ }^{2}-2 \mathrm{R}_{23} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right)
\end{gathered}
$$

where, $R_{23}=\frac{\bar{X} \beta_{1(x)}}{\overline{\mathrm{X}} \beta_{1(x)}+Q D}$.
Swain [21] proposed an alternative ratio estimator to the ratio type exponential estimator proposed by Bahl and Tuteja and the traditional ratio estimator as,

$$
\mathrm{t}_{24}=\overline{\mathrm{y}}\left(\frac{\overline{\mathrm{X}}}{\overline{\mathrm{x}}}\right)^{1 / 2}
$$

Both conceptually and numerically, bias and MSE with large sample approximations are found,

$$
\begin{gathered}
\operatorname{Bias}\left(\mathrm{t}_{24}\right)=\frac{1-\mathrm{f}}{8 \mathrm{n}} \overline{\mathrm{Y}}\left(3 \mathrm{C}_{\mathrm{x}}^{2}-4 \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right) \\
\operatorname{MSE}\left(\mathrm{t}_{24}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2}\left(\mathrm{C}_{\mathrm{y}}{ }^{2}+\frac{\mathrm{C}_{\mathrm{x}}{ }^{2}}{4}-\rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right)
\end{gathered}
$$

Jerajuddin and Kishun [22] presented a modified ratio estimator for estimating the $\overline{\mathrm{Y}}$ using the sample size picked from the population under SRSWOR.

$$
\mathrm{t}_{25}=\overline{\mathrm{y}}\left(\frac{\overline{\mathrm{X}}+\mathrm{n}}{\overline{\mathrm{x}}+\mathrm{n}}\right)
$$

The estimator's bias and MSE are calculated up to the first order of approximation,

$$
\begin{gathered}
\operatorname{Bias}\left(\mathrm{t}_{25}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}\left(\mathrm{R}_{25}{ }^{2} \mathrm{C}_{\mathrm{x}}{ }^{2}-\mathrm{R}_{25} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right) \\
\operatorname{MSE}\left(\mathrm{t}_{25}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2}\left(\mathrm{C}_{\mathrm{y}}{ }^{2}+\mathrm{R}_{25}{ }^{2} \mathrm{C}_{\mathrm{x}}{ }^{2}-2 \mathrm{R}_{25} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right)
\end{gathered}
$$

where $\mathrm{R}_{23}=\frac{\overline{\mathrm{x}}}{\overline{\mathrm{X}}+\mathrm{n}}$.
Soponviwatkul and Lawson[23] utilized a known population coefficient of variation of X , the correlation coefficient between Y and X , and the sample regression coefficient of Y on Xto estimate the $\overline{\mathrm{Y}}$ as,

$$
\begin{aligned}
& \mathrm{t}_{26}=\overline{\mathrm{y}}\left(\frac{\overline{\mathrm{X}}+\mathrm{C}_{\mathrm{x}}}{\overline{\mathrm{x}}+\mathrm{C}_{\mathrm{x}}}\right)^{\mathrm{b}_{1}} \\
& \mathrm{t}_{27}=\overline{\mathrm{y}}\left(\frac{\overline{\mathrm{x}}+\rho}{\overline{\mathrm{x}}+\rho}\right)^{\mathrm{b}_{1}}
\end{aligned}
$$

Up to the first order of approximation, equations for the bias and MSE of the proposed estimators have been obtained as,

$$
\begin{aligned}
\operatorname{Bias}\left(\mathrm{t}_{26}\right)= & \frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}\left(\frac{\mathrm{~b}_{1}\left(\mathrm{~b}_{1}+1\right)}{2} \mathrm{R}_{5}^{2} \mathrm{C}_{\mathrm{x}}^{2}-\mathrm{b}_{1} \mathrm{R}_{5} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right) \\
\operatorname{Bias}\left(\mathrm{t}_{27}\right)= & \frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}\left(\frac{\mathrm{~b}_{1}\left(\mathrm{~b}_{1}+1\right)}{2} \mathrm{R}_{11}^{2} \mathrm{C}_{\mathrm{x}}^{2}-\mathrm{b}_{1} \mathrm{R}_{11} \rho \mathrm{C}_{\mathrm{y}} \mathrm{C}_{\mathrm{x}}\right) \\
& \operatorname{MSE}\left(\mathrm{t}_{26}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2} \mathrm{C}_{\mathrm{y}}^{2}\left(1-\rho^{2}\right) \\
& \operatorname{MSE}\left(\mathrm{t}_{27}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2} \mathrm{C}_{\mathrm{y}}^{2}\left(1-\rho^{2}\right)
\end{aligned}
$$

Ijaz and Ali [24] suggested an effective estimator for estimating $\bar{Y}$. A modified ratio estimator with the same efficiency as a regression estimator has been developed. It is a wellknown fact that the linear regression estimator beats the majority of ratio estimators, the estimator is,

$$
\begin{gathered}
\mathrm{t}_{28}=\omega_{1} \overline{\mathrm{y}}+\left(1-\omega_{1}\right) \overline{\mathrm{y}}\left(\frac{\overline{\mathrm{x}}}{\overline{\mathrm{x}}}\right) \\
\mathrm{t}_{29}=\omega_{2} \overline{\mathrm{y}}+\left(1-\omega_{2}\right)\left(\overline{\mathrm{y}} \exp \frac{\overline{\mathrm{X}}-\overline{\mathrm{x}}}{\overline{\mathrm{x}}-\overline{\mathrm{X}}}\right)
\end{gathered}
$$

Up to first order of approximation, the Bias and minimum MSE have been determined,

$$
\begin{gathered}
\operatorname{Bias}\left(\mathrm{t}_{28}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}} \rho \mathrm{C}_{\mathrm{y}}\left(\mathrm{C}_{\mathrm{x}}-\rho\right) \\
\operatorname{Bias}\left(\mathrm{t}_{29}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}} \rho \mathrm{C}_{\mathrm{y}}\left(\frac{1}{4} \mathrm{C}_{\mathrm{x}}-\rho \mathrm{C}_{\mathrm{y}}\right) \\
\operatorname{MSE}\left(\mathrm{t}_{28}\right)=\operatorname{MSE}\left(\mathrm{t}_{29}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2} \mathrm{C}_{\mathrm{y}}^{2}\left(1-\rho^{2}\right)
\end{gathered}
$$

Yadav et al. [25] considered the enhanced estimator of $\bar{Y}$ using known auxiliary parameters as,

$$
\mathrm{t}_{30}=\overline{\mathrm{y}}\left(\frac{\mathrm{ab} \overline{\mathrm{x}}+\mathrm{cd}}{\mathrm{ab} \overline{\mathrm{x}}+\mathrm{cd}}\right)
$$

The Bias and MSE of the estimator is examined and calculated as,

$$
\begin{gathered}
\mathrm{B}\left(\mathrm{t}_{30}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}\left[\theta^{2} \mathrm{C}_{\mathrm{x}}^{2}-\theta \mathrm{C}_{\mathrm{yx}}\right] \\
\operatorname{MSE}\left(\mathrm{t}_{30}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2}\left(\mathrm{C}_{\mathrm{y}}^{2}-\frac{\mathrm{C}_{\mathrm{yx}}{ }^{2}}{\mathrm{C}_{\mathrm{x}}^{2}}\right)
\end{gathered}
$$

where $\theta=\frac{a b \overline{\bar{X}}}{a b \bar{X}+c d}$.
Yadav and Baghel [26] in instances where a Simple Random Sampling Scheme is used, in their work, they proposes a method for improving $\overline{\mathrm{Y}}$ estimation by utilizing information from an X and suggested a new class of estimators of $\overline{\mathrm{Y}}$ as,

$$
t_{31}=\alpha \bar{y}+(1-\alpha) \bar{y}\left[\frac{a b \bar{x}+c d}{a b \bar{x}+c d}\right]
$$

The Bias and MSE are calculated up to the first order of approximation. For the optimum value of the characterizing scaler, the least value of the MSE for the specified class of estimators is also calculated as,

$$
\begin{aligned}
\mathrm{B}\left(\mathrm{t}_{31}\right)= & \theta^{2} \mathrm{C}_{\mathrm{x}}^{2}-\overline{\mathrm{Y}}\left[\alpha\left(\theta \mathrm{C}_{\mathrm{yx}}-\theta^{2} \mathrm{C}_{\mathrm{x}}^{2}\right)+\left(\theta^{2} \mathrm{C}_{\mathrm{x}}^{2}-\theta \mathrm{C}_{\mathrm{yx}}\right)\right] \\
& \operatorname{MSE}\left(\mathrm{t}_{31}\right)=\frac{1-\mathrm{f}}{\mathrm{n}} \overline{\mathrm{Y}}^{2}\left(\mathrm{C}_{\mathrm{y}}{ }^{2}-\frac{\mathrm{C}_{\mathrm{yx}}^{2}}{\mathrm{C}_{\mathrm{x}}^{2}}\right)
\end{aligned}
$$

where $\theta=\frac{a b \overline{\bar{X}}}{a b \bar{X}+c d}$.
Yadav and Baghel [27] advocated for improved $\overline{\mathrm{Y}}$ estimation using a new class of estimators that use known information on an X under the SRS Scheme as,

$$
\mathrm{t}_{32}=\mathrm{k} \overline{\mathrm{y}}\left[\frac{\mathrm{ab} \overline{\mathrm{X}}+\mathrm{cd}}{\mathrm{ab} \overline{\mathrm{x}}+\mathrm{cd}}\right]
$$

The suggested class's Bias and MSE are calculated up to the first order of approximation. By optimizing the characterizing scalar, the values of Bias and the minimal MSE can be achieved as,

$$
\begin{aligned}
& \operatorname{Bias}\left(t_{32}\right)=\bar{Y}\left(\frac{A^{2}}{B}-1\right) \\
& \operatorname{MSE}\left(t_{32}\right)=\bar{Y}^{2}\left(1-\frac{A^{2}}{B}\right)
\end{aligned}
$$

where, $A=1-\theta \lambda C_{y x}+\theta^{2} \lambda C_{x}{ }^{2}$ andB $=1+\lambda C_{x}{ }^{2}+3 \theta^{2} \lambda C_{x}{ }^{2}-4 \theta \lambda C_{y x}$.

## 3. PROPOSED CLASS OF ESTIMATOR

Inspired by the literature of improved estimators, we suggest an improved class of ratio type estimators for the estimation $\overline{\mathrm{Y}}$ using the known auxiliary parameters as,

$$
\begin{equation*}
\mathrm{t}_{\mathrm{p}}=\mathrm{k}_{1} \overline{\mathrm{y}}+\mathrm{k}_{2} \overline{\mathrm{y}}\left[\frac{\mathrm{ab} \overline{\mathrm{X}}+\mathrm{cd}}{\mathrm{ab} \overline{\mathrm{x}}+\mathrm{cd}}\right] ; \mathrm{k}_{1}+\mathrm{k}_{2} \neq 1 \tag{1}
\end{equation*}
$$

where, $\mathrm{k}_{1}$ and $\mathrm{k}_{2}$ are characterizing constant and $\mathrm{a}, \mathrm{b}, \mathrm{c}$ and d are either constants or the known parameter of the auxiliary variable. The values of $k_{1}$ and $k_{2}$ are chosen such that the MSE of the suggested estimator is minimum. Some special cases.

Case 1. If $\mathrm{k}_{1}=0$ and $\mathrm{k}_{2}=1$, then MSE of the proposed estimator is same as that of [25].
Case 2.If $k_{1}=1$ and $k_{2}=0$, then MSE of the proposed estimator is same as that of mean per unit estimator.

Case 3. If $\mathrm{k}_{1}=0$, then MSE of the proposed estimator is same as that of [27].
Case 4. If $\mathrm{k}_{2}=0$, then MSE of the proposed estimator is same as that of [28].
Case 5. If $k_{1}+k_{2}=1$, then MSE of the proposed estimator is same as that of [26].

### 3.1. SOME MEMBERS OF THE PROPOSED FAMILY OF ESTIMATORS

- $\mathrm{t}_{\mathrm{p}(1)}=\mathrm{k}_{1} \overline{\mathrm{y}}+\mathrm{k}_{2} \overline{\mathrm{y}}\left[\frac{n \overline{\mathrm{X}}+\rho \mathrm{C}_{\mathrm{x}}}{\mathrm{n} \overline{\mathrm{x}}+\rho \mathrm{C}_{\mathrm{x}}}\right]$
- $t_{p(2)}=k_{1} \bar{y}+k_{2} \bar{y}\left[\frac{\beta_{1(x)} \mathrm{M}_{x} \overline{\mathrm{X}}+\rho}{\beta_{1(x)} \mathrm{M}_{\mathrm{x}} \overline{\mathrm{x}}+\rho}\right]$
- $t_{p(3)}=k_{1} \bar{y}+k_{2} \bar{y}\left[\frac{\beta_{1(x)} M_{x} \bar{X}+\rho C_{x}}{\beta_{1(x)} M_{x} \overline{\mathrm{x}}+\rho \mathrm{C}_{\mathrm{x}}}\right]$
- $t_{p(4)}=k_{1} \bar{y}+k_{2} \bar{y}\left[\frac{\beta_{1(x)} M_{x} \bar{x}+\rho C_{y x}}{n \beta_{1(x)} M_{x}+\rho C_{y x}}\right]$
- $\mathrm{t}_{\mathrm{p}(5)}=\mathrm{k}_{1} \overline{\mathrm{y}}+\mathrm{k}_{2} \overline{\mathrm{y}}\left[\frac{\beta_{2(\mathrm{x})} \mathrm{M}_{\mathrm{x}} \overline{\mathrm{X}}+\rho \mathrm{C}_{\mathrm{x}}}{\beta_{2(\mathrm{x})} \mathrm{M}_{\mathrm{x}} \overline{\mathrm{x}}+\rho \mathrm{C}_{\mathrm{x}}}\right]$


### 3.2. BIAS AND MSE OF THE PROPOSED ESTIMATOR

The following approximations are used to obtain the Bias and MSE of the suggested estimator,

$$
\overline{\mathrm{y}}=\overline{\mathrm{Y}}\left(1+\mathrm{e}_{0}\right)
$$

and

$$
\overline{\mathrm{x}}=\overline{\mathrm{X}}\left(1+\mathrm{e}_{1}\right)
$$

such that

$$
\mathrm{E}\left(\mathrm{e}_{0}\right)=\mathrm{E}\left(\mathrm{e}_{1}\right)=0
$$

and

$$
\mathrm{E}\left(\mathrm{e}_{0}^{2}\right)=\lambda \mathrm{C}_{\mathrm{y}}^{2}, \mathrm{E}\left(\mathrm{e}_{1}^{2}\right)=\lambda \mathrm{C}_{\mathrm{x}}^{2}, \mathrm{E}\left(\mathrm{e}_{0} \mathrm{e}_{1}\right)=\lambda \mathrm{C}_{\mathrm{yx}}
$$

Now, expressing the $t_{p}$ in terms ofe $e_{0}$ and $e_{1}$, we have,

$$
\mathrm{t}_{\mathrm{p}}=\mathrm{k}_{1} \overline{\mathrm{Y}}\left(1+\mathrm{e}_{0}\right)+\mathrm{k}_{2} \overline{\mathrm{Y}}\left(1+\mathrm{e}_{0}\right)\left[\frac{\mathrm{ab} \overline{\mathrm{X}}+\mathrm{cd}}{\mathrm{ab} \overline{\mathrm{X}}\left(1+\mathrm{e}_{1}\right)+\mathrm{cd}}\right]
$$

Simplifying the above equation, we get,

$$
\begin{gather*}
t_{p}=k_{1} \overline{\mathrm{Y}}\left(1+e_{0}\right)+k_{2} \overline{\mathrm{Y}}\left(1+e_{0}\right)\left[\frac{a b \overline{\mathrm{X}}+c d}{a b \overline{\mathrm{X}}+\mathrm{ab} \overline{\mathrm{X}} \mathrm{e}_{1}+c \mathrm{~cd}}\right] \\
\mathrm{t}_{\mathrm{p}}=\mathrm{k}_{1} \overline{\mathrm{Y}}\left(1+\mathrm{e}_{0}\right)+\mathrm{k}_{2} \overline{\mathrm{Y}}\left(1+\mathrm{e}_{0}\right)\left[\frac{1}{\left.1+\frac{a b \overline{\mathrm{X}} e_{1}}{\mathrm{ab} \overline{\mathrm{X}}+\mathrm{cd}}\right]}\right.  \tag{2}\\
\mathrm{t}_{\mathrm{p}}=\mathrm{k}_{1} \overline{\mathrm{Y}}\left(1+\mathrm{e}_{0}\right)+\mathrm{k}_{2} \overline{\mathrm{Y}}\left(1+\mathrm{e}_{0}\right)\left(1+\theta \mathrm{e}_{1}\right)^{-1}
\end{gather*}
$$

where $\theta=\frac{a b \bar{X}}{a b \bar{X}+c d}$.
Expanding the equation (2), simplifying, and retaining the terms up to the first order of approximation, we get,

$$
\begin{gather*}
t_{p}=k_{1} \overline{\mathrm{Y}}\left(1+\mathrm{e}_{0}\right)+\mathrm{k}_{2} \overline{\mathrm{Y}}\left(1+\mathrm{e}_{0}\right)\left(1-\theta \mathrm{e}_{1}+\theta^{2} \mathrm{e}_{1}{ }^{2}\right) \\
\mathrm{t}_{\mathrm{p}}=\mathrm{k}_{1} \overline{\mathrm{Y}}\left(1+\mathrm{e}_{0}\right)+\mathrm{k}_{2} \mathrm{Y}\left(1-\theta \mathrm{e}_{1}+\theta^{2} \mathrm{e}_{1}{ }^{2}+\mathrm{e}_{0}+\theta \mathrm{e}_{0} \mathrm{e}_{1}\right) \\
\mathrm{t}_{\mathrm{p}}=\overline{\mathrm{Y}}\left[\mathrm{k}_{1}\left(1+\mathrm{e}_{0}\right)+\mathrm{k}_{2}\left(1-\theta \mathrm{e}_{1}+\theta^{2} \mathrm{e}_{1}{ }^{2}+\mathrm{e}_{0}+\theta \mathrm{e}_{0} \mathrm{e}_{1}\right)\right]  \tag{3}\\
\mathrm{t}_{\mathrm{p}}-\overline{\mathrm{Y}}=\overline{\mathrm{Y}}\left[\mathrm{k}_{1}\left(1+\mathrm{e}_{0}\right)+\mathrm{k}_{2}\left(1-\theta \mathrm{e}_{1}+\theta^{2} \mathrm{e}_{1}{ }^{2}+\mathrm{e}_{0}+\theta \mathrm{e}_{0} \mathrm{e}_{1}\right)-1\right]
\end{gather*}
$$

Taking expectation on the both sides of the equation (3),

$$
\begin{gather*}
\mathrm{E}\left(\mathrm{t}_{\mathrm{p}}-\overline{\mathrm{Y}}\right)=\overline{\mathrm{Y}}\left[\mathrm{k}_{1}\left(1+\mathrm{E}\left(\mathrm{e}_{0}\right)\right)\right. \\
+\mathrm{k}_{2}\left(1-\theta \mathrm{E}\left(\mathrm{e}_{1}\right)+\theta^{2} \mathrm{E}\left(\mathrm{e}_{1}{ }^{2}\right)+\mathrm{E}\left(\mathrm{e}_{0}\right)-\theta \mathrm{E}\left(\mathrm{e}_{0} \mathrm{e}_{1}\right)-1\right]  \tag{4}\\
\operatorname{Bias}\left(\mathrm{t}_{\mathrm{p}}\right)=\overline{\mathrm{Y}}\left[\mathrm{k}_{1}+\mathrm{k}_{2}\left(1+\theta^{2} \lambda \mathrm{C}_{\mathrm{x}}{ }^{2}-\theta \lambda \mathrm{C}_{\mathrm{yx}}\right)-1\right]
\end{gather*}
$$

Squaring the equation (3), taking the expectation, and retaining the terms up to the first order of approximation, we get,

$$
E\left(t_{p}-\bar{Y}\right)^{2}=\bar{Y}^{2} E\left[k_{1}\left(1+e_{0}\right)+k_{2}\left(1-\theta e_{1}+\theta^{2} e_{1}^{2}+e_{0}-\theta e_{0} e_{1}\right)-1\right]^{2}
$$

On expanding the above equation, we get,

$$
\begin{align*}
\mathrm{E}\left(\mathrm{t}_{\mathrm{p}}-\overline{\mathrm{Y}}\right)^{2}= & \overline{\mathrm{Y}}^{2} \\
& \mathrm{E}\left[\mathrm{k}_{1}{ }^{2}\left(1+\mathrm{e}_{0}\right)^{2}+\mathrm{k}_{2}^{2}\left(1-\theta \mathrm{e}_{1}+\theta^{2} \mathrm{e}_{1}{ }^{2}+\mathrm{e}_{0}-\theta \mathrm{e}_{0} \mathrm{e}_{1}\right)^{2}+1\right. \\
& +2\left\{\mathrm{k}_{1} \mathrm{k}_{2}\left(1+\mathrm{e}_{0}\right)\left(1-\theta \mathrm{e}_{1}+\theta^{2} \mathrm{e}_{1}{ }^{2}+\mathrm{e}_{0}-\theta \mathrm{e}_{0} \mathrm{e}_{1}\right)\right. \\
& \left.\left.-\mathrm{k}_{2}\left(1-\theta \mathrm{e}_{1}+\theta^{2} \mathrm{e}_{1}{ }^{2}+\mathrm{e}_{0}-\theta \mathrm{e}_{0} \mathrm{e}_{1}\right)+\mathrm{k}_{1}\left(1+\mathrm{e}_{0}\right)\right\}\right]  \tag{5}\\
\mathrm{E}\left(\mathrm{t}_{\mathrm{p}}-\overline{\mathrm{Y}}\right)^{2}= & \overline{\mathrm{Y}}^{2} E\left[\mathrm{k}_{1}{ }^{2}\left(1+\mathrm{e}_{0}\right)^{2}+\mathrm{k}_{2}{ }^{2}\left\{1+\theta^{2} \mathrm{e}_{1}{ }^{2}+\mathrm{e}_{0}{ }^{2}+2\left(-\theta \mathrm{e}_{1}+\theta^{2} \mathrm{e}_{1}{ }^{2}+\mathrm{e}_{0}\right.\right.\right. \\
& \left.\left.-\theta \mathrm{e}_{0} \mathrm{e}_{1}-\theta \mathrm{e}_{0} \mathrm{e}_{1}\right)\right\}+1 \\
& +2\left\{\mathrm{k}_{1} \mathrm{k}_{2}\left(1-\theta \mathrm{e}_{1}+\theta^{2} \mathrm{e}_{1}{ }^{2}+\mathrm{e}_{0}-\theta \mathrm{e}_{0} \mathrm{e}_{1}+\mathrm{e}_{0}-\theta \mathrm{e}_{0} \mathrm{e}_{1}+\mathrm{e}_{0}{ }^{2}\right)\right. \\
& \left.\left.-\mathrm{k}_{2}\left(1-\theta \mathrm{e}_{1}+\theta^{2} \mathrm{e}_{1}{ }^{2}+\mathrm{e}_{0}-\theta \mathrm{e}_{0} \mathrm{e}_{1}\right)+\mathrm{k}_{1}\left(1+\mathrm{e}_{0}\right)\right\}\right]
\end{align*}
$$

$$
\begin{aligned}
\mathrm{E}\left(\mathrm{t}_{\mathrm{p}}-\overline{\mathrm{Y}}\right)^{2}= & \overline{\mathrm{Y}}^{2}\left[\mathrm{k}_{1}^{2}\left(1+\lambda \mathrm{C}_{\mathrm{y}}^{2}\right)+\mathrm{k}_{2}{ }^{2}\left(1+\theta^{2} \lambda \mathrm{C}_{\mathrm{x}}{ }^{2}+\lambda \mathrm{C}_{\mathrm{y}}{ }^{2}+2\left(\theta^{2} \lambda \mathrm{C}_{\mathrm{x}}{ }^{2}-2 \theta \lambda \mathrm{C}_{\mathrm{yx}}\right)\right)\right. \\
& +2\left\{\mathrm{k}_{1} \mathrm{k}_{2}\left(1+\theta^{2} \lambda \mathrm{C}_{\mathrm{x}}{ }^{2}-\theta \lambda \mathrm{C}_{\mathrm{yx}}-\theta \lambda \mathrm{C}_{\mathrm{yx}}+\lambda \mathrm{C}_{\mathrm{y}}^{2}\right)\right. \\
& \left.\left.-\mathrm{k}_{2}\left(1+\theta^{2} \lambda \mathrm{C}_{\mathrm{x}}{ }^{2}+\theta \lambda \mathrm{C}_{\mathrm{yx}}\right)-2 \mathrm{k}_{1}\right\}\right]
\end{aligned}
$$

$$
\begin{aligned}
\operatorname{MSE}\left(\mathrm{t}_{\mathrm{p}}\right)= & \overline{\mathrm{Y}}^{2}\left[\mathrm{k}_{1}{ }^{2}\left(1+\lambda \mathrm{C}_{\mathrm{y}}{ }^{2}\right)+\mathrm{k}_{2}{ }^{2}\left(1+3 \theta^{2} \lambda \mathrm{C}_{\mathrm{x}}{ }^{2}+\lambda \mathrm{C}_{\mathrm{y}}{ }^{2}-4 \theta \lambda \mathrm{C}_{\mathrm{yx}}\right)+1\right. \\
& +2 \mathrm{k}_{1} \mathrm{k}_{2}\left(1+\theta^{2} \lambda \mathrm{C}_{\mathrm{x}}{ }^{2}+\lambda \mathrm{C}_{\mathrm{y}}{ }^{2}-2 \theta \lambda \mathrm{C}_{\mathrm{yx}}\right)-2 \mathrm{k}_{2}\left(1+\theta^{2} \lambda \mathrm{C}_{\mathrm{x}}{ }^{2}-\theta \lambda \mathrm{C}_{\mathrm{yx}}\right) \\
& \left.-2 \mathrm{k}_{1}\right]
\end{aligned}
$$

Let,
$\mathrm{A}=1+\lambda \mathrm{C}_{\mathrm{y}}{ }^{2}$
$B=1+3 \theta^{2} \lambda C_{x}{ }^{2}+\lambda C^{2}{ }^{2}-4 \theta \lambda C_{y x}$
$\mathrm{C}=1+\theta^{2} \lambda \mathrm{C}_{\mathrm{x}}{ }^{2}+\lambda \mathrm{C}_{\mathrm{y}}{ }^{2}-2 \theta \lambda \mathrm{C}_{\mathrm{yx}}$
$D=1+\theta^{2} \lambda C_{x}{ }^{2}-\theta \lambda C_{y x}$
Rewriting the equation (5) in the terms of $\mathrm{A}, \mathrm{B}, \mathrm{C}$ and D , we get,

$$
\begin{equation*}
\operatorname{MSE}\left(\mathrm{t}_{\mathrm{p}}\right)=\overline{\mathrm{Y}}^{2}\left[\mathrm{Ak}_{1}^{2}+\mathrm{Bk}_{2}^{2}+2 \mathrm{Ck}_{1} \mathrm{k}_{2}-2 \mathrm{k}_{1}-2 \mathrm{Dk}_{2}+1\right] \tag{6}
\end{equation*}
$$

The optimum value of $\mathrm{k}_{1}$ and $\mathrm{k}_{2}$ are obtained by,

$$
\frac{\partial \operatorname{MSE}\left(\mathrm{t}_{\mathrm{p}}\right)}{\partial \mathrm{k}_{1}}=0 \text { and } \frac{\partial \operatorname{MSE}\left(\mathrm{t}_{\mathrm{p}}\right)}{\partial \mathrm{k}_{1}}=0
$$

which gives,

$$
\mathrm{k}_{1(\mathrm{opt})}=\frac{\mathrm{CD}-\mathrm{B}}{\mathrm{C}^{2}-\mathrm{AB}} \text { and } \mathrm{k}_{2(\mathrm{opt})}=\frac{\mathrm{C}-\mathrm{AD}}{\mathrm{C}^{2}-\mathrm{AB}}
$$

The minimum MSE for the optimum value of $k_{1}$ and $k_{2}$ is given by,

$$
\begin{array}{r}
\operatorname{MSE}\left(\mathrm{t}_{\mathrm{p}}\right)_{\min }=\overline{\mathrm{Y}}^{2}\left[1+\mathrm{A}\left(\frac{\mathrm{CD}-\mathrm{B}}{\mathrm{C}^{2}-\mathrm{AB}}\right)^{2}+\mathrm{B}\left(\frac{\mathrm{C}-\mathrm{AD}}{\mathrm{C}^{2}-\mathrm{AB}}\right)^{2}\right. \\
\left.+2\left(\frac{\mathrm{CD}-\mathrm{B}}{\mathrm{C}^{2}-\mathrm{AB}}\right)\left(\frac{\mathrm{C}-\mathrm{AD}}{\mathrm{C}^{2}-\mathrm{AB}}\right)-2\left(\frac{\mathrm{CD}-\mathrm{B}}{\mathrm{C}^{2}-\mathrm{AB}}\right)-2 \mathrm{D}\left(\frac{\mathrm{C}-\mathrm{AD}}{\mathrm{C}^{2}-\mathrm{AB}}\right)\right] \\
=\overline{\mathrm{Y}}^{2}\left[\begin{array}{c}
{[\mathrm{CD}-\mathrm{CD}-\mathrm{B})^{2}+\mathrm{B}(\mathrm{C}-\mathrm{AD})^{2}+2 \mathrm{C}(\mathrm{CD}-\mathrm{B})(\mathrm{C}-\mathrm{AD})} \\
\left.1+\frac{\left.-2\left(\mathrm{C}^{2}-\mathrm{AB}\right)(\mathrm{CD}-\mathrm{B})-2 \mathrm{D}\left(\mathrm{C}^{2}-\mathrm{AB}\right)(\mathrm{C}-\mathrm{AD})\right]}{\left(\mathrm{C}^{2}-\mathrm{AB}\right)^{2}}\right] \\
\operatorname{MSE}\left(\mathrm{t}_{\mathrm{p}}\right)_{\min }=\overline{\mathrm{Y}}^{2}\left[1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right]
\end{array}\right.
\end{array}
$$

where,

$$
\begin{aligned}
& \mathrm{P}=\left[\mathrm{A}(\mathrm{CD}-\mathrm{B})^{2}+\mathrm{B}(\mathrm{C}-\mathrm{AD})^{2}+2 \mathrm{C}(\mathrm{CD}-\mathrm{B})(\mathrm{C}-\mathrm{AD})-2\left(\mathrm{C}^{2}-\mathrm{AB}\right)(\mathrm{CD}-\mathrm{B})\right. \\
&\left.\mathrm{Q}=\left(\mathrm{C}^{2}-\mathrm{AB}\right) \quad-2 \mathrm{D}\left(\mathrm{C}^{2}-A B\right)(\mathrm{C}-\mathrm{AD})\right]
\end{aligned}
$$

## 4. COMPARISONS OF EFFICIENCIES

The proposed class of estimators is compared to existing ratio-type estimators of $\bar{Y}$ in this section and the conditions under which it outperforms existing estimators are listed in Table 3. The following criterion must be met for the proposed class to be more efficient than existing estimators:

$$
\operatorname{MSE}\left(\mathrm{t}_{\mathrm{i}}\right)-\operatorname{MSE}\left(\mathrm{t}_{\mathrm{p}}\right)>0 ; i=0,1, \ldots, 32
$$

Table 3. Efficiency comparison.

| Estimator | Efficiency Condition |
| :---: | :---: |
| $\mathbf{t}_{0}$ Mean per unit estimator | $\lambda C_{y}{ }^{2}-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathbf{t}_{1}$ Watson [1] estimator | $\lambda \mathrm{C}_{\mathrm{y}}{ }^{2}\left(1-\rho^{2}\right)-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathbf{t}_{2}$ Cochran [2] estimator | $\lambda\left[C_{y}{ }^{2}+C_{x}{ }^{2}-2 \rho C_{y} C_{x}\right]-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathbf{t}_{3}$ Goodman [3] estimator | $\lambda\left[C_{y}{ }^{2}+C_{x}{ }^{2}-2 \rho C_{y} C_{x}\right]-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathbf{t}_{4}$ Chakrabarty [4] estimator | $\lambda\left[C_{y}{ }^{2}+\alpha^{2} C_{x}{ }^{2}-2 \alpha \rho C_{y} C_{x}\right]-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathbf{t}_{5}$ Sahai and Ray [5] estimator | $\lambda\left[C_{y}^{2}+\omega^{2} C_{x}^{2}-2 \omega \rho C_{y} C_{x}\right]-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathbf{t}_{6}$ Sisodia [6]estimator | $\lambda\left[C_{y}{ }^{2}+R_{6}{ }^{2} C_{x}{ }^{2}-2 R_{6} \rho C_{y} C_{x}\right]-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathbf{t}_{7} \mathrm{Bahl}$ and Tuteja [7] estimator | $\lambda\left[C_{y}{ }^{2}+\frac{C_{x}^{2}}{4}-\rho C_{y} C_{x}\right]-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathbf{t}_{\mathbf{8}}$ Upadhyaya and Singh [8] estimator | $\lambda\left[C_{y}{ }^{2}+R_{8}{ }^{2} C_{x}{ }^{2}-2 R_{8} \rho C_{y} C_{x}\right]-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathbf{t}_{9}$ Kadilar and Cingi [9] estimator | $\lambda\left[C_{y}^{2}+4 C_{x}{ }^{2}-4 \rho C_{y} C_{x}\right]-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathbf{t}_{\mathbf{1 0}}$ Singh [10] estimator | $\lambda\left[C_{y}{ }^{2}+R_{10}{ }^{2} C_{x}{ }^{2}-2 R_{10} \rho C_{y} C_{x}\right]-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathbf{t}_{\mathbf{1 1}}$ Singh and Tailor [14] estimator | $\lambda\left[C_{y}{ }^{2}+R_{11}{ }^{2} C_{x}{ }^{2}-2 R_{11} \rho C_{y} C_{x}\right]-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathrm{t}_{12}$ Singh et al. [11] estimator | $\lambda\left[C_{y}{ }^{2}+R_{12}{ }^{2} C_{x}{ }^{2}-2 R_{12} \rho C_{y} C_{x}\right]-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathrm{t}_{13}$ Singh and Tailor [12] estimator | $\lambda \mathrm{C}_{\mathrm{y}}{ }^{2}\left(1-\rho^{2}\right)-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathbf{t}_{14}$ Kadilar and Cingi [13] estimator | $\lambda\left[C_{y}{ }^{2}+R_{14}{ }^{2} C_{x}{ }^{2}-2 R_{14} \rho C_{y} C_{x}\right]-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathrm{t}_{15}$ Khoshnevisan et al.[15] estimator | $\lambda C_{y}^{2}\left(1-\rho^{2}\right)-\left(1+\frac{P}{Q^{2}}\right)>0$ |
| $\mathbf{t}_{16}$ Al-Omari et al. [16] estimator | $\lambda\left[C_{y}{ }^{2}+R_{16}{ }^{2} C_{x}{ }^{2}-2 R_{16} \rho C_{y} C_{x}\right]-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathrm{t}_{17} \mathrm{Yan}$ and Tian [17] estimator | $\lambda\left[C_{y}{ }^{2}+R_{17}{ }^{2} C_{x}{ }^{2}-2 R_{17} \rho C_{y} C_{x}\right]-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathbf{t i 8}_{\mathbf{8}} \mathrm{Yan}$ and Tian [17] estimator | $\lambda\left[C_{y}{ }^{2}+R_{18}{ }^{2} C_{x}{ }^{2}-2 R_{18} \rho C_{y} C_{x}\right]-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathbf{t}_{19} \mathrm{Yan}$ and Tian [17]) estimator | $\lambda\left[C_{y}{ }^{2}+R_{19}{ }^{2} C_{x}{ }^{2}-2 R_{19} \rho C_{y} C_{x}\right]-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathbf{t a O}_{\mathbf{0}} \mathrm{Yan}$ and Tian [17] estimator | $\lambda\left[C_{y}{ }^{2}+R_{20}{ }^{2} C_{x}^{2}-2 R_{20} \rho C_{y} C_{x}\right]-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathbf{t}_{\mathbf{2 1}}$ Pandey et al. [18] estimator | $\lambda\left[C_{y}{ }^{2}+k^{2} C_{x}^{2}-2 k \rho C_{y} C_{x}\right]-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathbf{t}_{22}$ Subramani and Kumarpandiyan [19] estimator | $\lambda\left[C_{y}{ }^{2}+R_{22}{ }^{2} C_{x}{ }^{2}-2 R_{22} \rho C_{y} C_{x}\right]-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |


| Estimator | Efficiency Condition |
| :--- | :---: |
| $\mathbf{t}_{\mathbf{2 3}}$ Jeelani et al. [20] estimator | $\lambda\left[C_{y}{ }^{2}+R_{23}{ }^{2} C_{x}{ }^{2}-2 R_{23} \rho C_{y} C_{x}\right]-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathbf{t}_{\mathbf{2 4}}$ Swain [21] estimator | $\lambda\left[C_{y}{ }^{2}+\frac{C_{x}{ }^{2}}{4}-\rho C_{y} C_{x}\right]-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathbf{t}_{\mathbf{2 5}}$ Jerajuddin and Kishun [22] estimator | $\lambda\left[C_{y}{ }^{2}+R_{25}{ }^{2} C_{x}{ }^{2}-2 R_{25} \rho C_{y} C_{x}\right]-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathbf{t}_{\mathbf{2 6}}$ Soponviwatkul and Lawson [23] estimator | $\lambda C_{\mathrm{y}}{ }^{2}\left(1-\rho^{2}\right)-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathbf{t}_{\mathbf{2 7}}$ Soponviwatkul and Lawson [23] estimator | $\lambda C_{\mathrm{y}}{ }^{2}\left(1-\rho^{2}\right)-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathbf{t}_{\mathbf{2 8}}$ Ijaz and Ali [24] estimator | $\lambda C_{\mathrm{y}}{ }^{2}\left(1-\rho^{2}\right)-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathbf{t}_{\mathbf{2 9}}$ Ijaz and Ali [24] estimator | $\lambda C_{\mathrm{y}}{ }^{2}\left(1-\rho^{2}\right)-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathbf{t}_{\mathbf{3 0}}$ Yadav et al. [25] estimator | $\lambda\left[C_{y}{ }^{2}-\frac{C_{y x}{ }^{2}}{C_{x}{ }^{2}}\right]-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathbf{t}_{\mathbf{3 1}}$ Yadav and Baghel [26] estimator | $\lambda\left[C_{y}{ }^{2}-\frac{C_{y x}{ }^{2}}{C_{x}{ }^{2}}\right]-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |
| $\mathbf{t}_{\mathbf{3 2}}$ Yadav and Baghel [27] estimator | $\left(1-\frac{A^{2}}{\mathrm{~B}}\right)-\left(1+\frac{\mathrm{P}}{\mathrm{Q}^{2}}\right)>0$ |

## 5. COMPUTATIONAL STUDY

We conducted a detailed computational analysis under two headings to demonstrate the advantages of our propositions: numerical study using real data sets and simulation study using artificially produced data sets.

### 5.1. NUMERICAL STUDY

We conducted a numerical analysis with two different real populations, which are described below:

1. Data Source: Singh and Chaudhary [29]

Data Details: Study Variable: Area under wheat in a region during year 1974
Auxiliary Variable: Cultivated Area under wheat in a region during year 1973
Table 4. Parameters of the first real population

| Parameter | Data Set | Parameter | Data Set |
| :---: | :---: | :---: | :---: |
| N | 34 | $\mathrm{C}_{\mathrm{yx}}$ | 0.5318817 |
| n | 5 | $\beta_{1(\mathrm{x})}$ | 0.8732281 |
| $\overline{\mathbf{Y}}$ | 199.4412 | $\beta_{2(\mathrm{x})}$ | 5.912272 |
| $\overline{\mathbf{X}}$ | 208.8824 | f | 0.1470588 |
| $\mathbf{S}_{\mathbf{y}}$ | 150.215 | $\lambda$ | 0.1705882 |
| $\mathbf{S}_{\mathbf{x}}$ | 150.506 | $\mathrm{Q}_{1(\mathrm{x})}$ | 94.25 |
| $\mathbf{C}_{\mathbf{y}}$ | 0.7531797 | $\mathrm{Q}_{3(\mathrm{x})}$ | 275.75 |
| $\mathbf{C}_{\mathbf{x}}$ | 0.7205298 | $\mathrm{Q}_{\mathrm{r}(\mathrm{x})}$ | 160.5 |
| $\mathbf{M}_{\mathbf{y}}$ | 142.5 | $\mathrm{Q}_{\mathrm{a}(\mathrm{x})}$ | 1666.3333 |
| $\mathbf{M}_{\mathbf{x}}$ | 150 | QD | 80.25 |
| $\mathbf{\rho}$ | 0.9800867 | TM | 162.25 |

The Percent Relative Efficiency (PRE) for different estimators with respect to proposed estimator is as follows:

$$
\operatorname{PRE}=\frac{\operatorname{MSE}\left(\mathrm{t}_{\mathrm{i}}\right)}{\operatorname{MSE}\left(\mathrm{t}_{\mathrm{p}(1)}\right)} \times 100
$$

Table 5. Comparison of ratio estimators of for real population-I

| Estimator | MSE | PRE | Estimator | MSE | PRE |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathbf{t}_{\mathbf{0}}$ | 3849.248 | 2537.823 | $\mathbf{t}_{\mathbf{1 9}}$ | 155.0032 | 102.1942 |
| $\mathbf{t}_{\mathbf{1}}$ | 151.7761 | 100.0665 | $\mathbf{t}_{\mathbf{2 0}}$ | 154.0141 | 101.542 |
| $\mathbf{t}_{\mathbf{2}}$ | 153.8903 | 101.4604 | $\mathbf{t}_{\mathbf{2 1}}$ | 151.7761 | 100.0665 |
| $\mathbf{t}_{\mathbf{3}}$ | 153.8903 | 101.4604 | $\mathbf{t}_{\mathbf{2 2}}$ | 1117.772 | 736.9511 |
| $\mathbf{t}_{\mathbf{4}}$ | 151.7761 | 100.0665 | $\mathbf{t}_{\mathbf{2 3}}$ | 535.4869 | 353.0484 |
| $\mathbf{t}_{\mathbf{5}}$ | 151.7761 | 100.0665 | $\mathbf{t}_{\mathbf{2 4}}$ | 1120.881 | 739.0008 |
| $\mathbf{t}_{\mathbf{6}}$ | 154.5253 | 101.8791 | $\mathbf{t}_{\mathbf{2 5}}$ | 159.8505 | 105.3900 |
| $\mathbf{t}_{\mathbf{7}}$ | 1120.881 | 739.0008 | $\mathbf{t}_{\mathbf{2 6}}$ | 151.7761 | 100.0665 |
| $\mathbf{t}_{\mathbf{8}}$ | 153.9922 | 101.5276 | $\mathbf{t}_{\mathbf{2 7}}$ | 151.7761 | 100.0665 |
| $\mathbf{t}_{\mathbf{9}}$ | 3504.046 | 2310.230 | $\mathbf{t}_{\mathbf{2 8}}$ | 151.7761 | 100.0665 |
| $\mathbf{t}_{\mathbf{1 0}}$ | 951.9383 | 627.6163 | $\mathbf{t}_{\mathbf{2 9}}$ | 151.7761 | 100.0665 |
| $\mathbf{t}_{\mathbf{1 1}}$ | 154.7732 | 102.0425 | $\mathbf{t}_{\mathbf{3 0}}$ | 151.7762 | 100.0666 |
| $\mathbf{t}_{\mathbf{1 2}}$ | 161.3102 | 106.3524 | $\mathbf{t}_{\mathbf{3 1}}$ | 151.7762 | 100.0666 |
| $\mathbf{t}_{\mathbf{1 3}}$ | 151.7761 | 100.0665 | $\mathbf{t}_{\mathbf{3 2}}$ | 152.776 | 100.7257 |
| $\mathbf{t}_{\mathbf{1 4}}$ | 155.1545 | 102.2939 | $\mathbf{t}_{\mathbf{p} \mathbf{( 1 )}}$ | 151.6828 | 100.005 |
| $\mathbf{t}_{\mathbf{1 5}}$ | 151.7761 | 100.0665 | $\mathbf{t}_{\mathbf{p} \mathbf{( 2 )}}$ | 151.6756 | 100.0003 |
| $\mathbf{t}_{\mathbf{1 6}}$ | 1392.582 | 918.1343 | $\mathbf{t}_{\mathbf{p} \mathbf{( 3 )}}$ | 151.6755 | 100.0002 |
| $\mathbf{t}_{\mathbf{1 7}}$ | 154.6699 | 101.9744 | $\mathbf{t}_{\mathbf{p}(\mathbf{4})}$ | 151.6754 | 100.0001 |
| $\mathbf{t}_{\mathbf{1 8}}$ | 162.7817 | 107.3226 | $\mathbf{t}_{\mathbf{p}(\mathbf{5})}$ | 151.6752 | 100.0000 |

## 2. Data Source: Yadav et al. [25]

Data Details: Study Variable: The production (Yield) of peppermint oil in kilogram Auxiliary Variable: The area of the field in Bigha (2529.3 Square Meter)

Table 6. Parameters of the second real population

| Parameter | Data Set | Parameter | Data Set |
| :---: | :---: | :---: | :---: |
| $N$ | 150 | $\mathbf{C}_{\mathbf{y x}}$ | 0.508802 |
| n | 40 | $\boldsymbol{\beta}_{\mathbf{1 ( x )}}$ | 2.801407 |
| $\overline{\mathbf{Y}}$ | 33.462 | $\boldsymbol{\beta}_{\mathbf{2 ( x )}}$ | 16.44023 |
| $\overline{\mathbf{X}}$ | 4.204667 | $\mathbf{f}$ | 0.2666667 |
| $\mathbf{S}_{\mathbf{y}}$ | 25.50316 | $\boldsymbol{\lambda}$ | 0.018333 |
| $\mathbf{S}_{\mathbf{x}}$ | 3.080385 | $\mathbf{Q}_{\mathbf{1}(\mathbf{x})}$ | 2 |
| $\mathbf{C}_{\mathbf{y}}$ | 0.762153 | $\mathbf{Q}_{\mathbf{3}(\mathbf{x})}$ | 5 |
| $\mathbf{C}_{\mathbf{x}}$ | 0.732611 | $\mathbf{Q}_{\mathbf{r}(\mathbf{x})}$ | 3 |
| $\mathbf{M}_{\mathbf{y}}$ | 25 | $\mathbf{Q}_{\mathbf{a}(\mathbf{x})}$ | 3.5 |
| $\mathbf{M}_{\mathbf{x}}$ | 3 | $\mathbf{Q D}$ | 1.5 |
| $\mathbf{\rho}$ | 0.911241 | TM | 3.25 |

Table 7. Comparisons of ratio estimators of population mean for real population-II

| Estimator | MSE | PRE | Estimator | MSE | PRE |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathbf{t}_{\mathbf{0}}$ | 11.92421 | 591.1532 | $\mathbf{t}_{\mathbf{1 9}}$ | 4.006074 | 198.6046 |
| $\mathbf{t}_{\mathbf{1}}$ | 2.022821 | 100.2831 | $\mathbf{t}_{\mathbf{2 0}}$ | 2.024702 | 100.3764 |
| $\mathbf{t}_{\mathbf{2}}$ | 2.052629 | 101.7609 | $\mathbf{t}_{\mathbf{2 1}}$ | 2.022821 | 100.2831 |
| $\mathbf{t}_{\mathbf{3}}$ | 2.052629 | 101.7609 | $\mathbf{t}_{\mathbf{2 2}}$ | 4.169214 | 206.6924 |
| $\mathbf{t}_{\mathbf{4}}$ | 2.022821 | 100.2831 | $\mathbf{t}_{\mathbf{2 3}}$ | 2.063746 | 102.312 |
| $\mathbf{t}_{\mathbf{5}}$ | 2.022821 | 100.2831 | $\mathbf{t}_{\mathbf{2 4}}$ | 4.233986 | 209.9036 |
| $\mathbf{t}_{\mathbf{6}}$ | 2.125144 | 105.3559 | $\mathbf{t}_{\mathbf{2 5}}$ | 10.03694 | 497.5901 |


| Estimator | MSE | PRE | Estimator | MSE | PRE |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathbf{t}_{\mathbf{7}}$ | 4.143891 | 205.437 | $\mathbf{t}_{\mathbf{2 6}}$ | 2.022821 | 100.2831 |
| $\mathbf{t}_{\mathbf{8}}$ | 2.041821 | 101.2251 | $\mathbf{t}_{\mathbf{2 7}}$ | 2.022821 | 100.2831 |
| $\mathbf{t}_{\mathbf{9}}$ | 14.21651 | 704.796 | $\mathbf{t}_{\mathbf{2 8}}$ | 2.022821 | 100.2831 |
| $\mathbf{t}_{\mathbf{1 0}}$ | 2.288509 | 113.4548 | $\mathbf{t}_{\mathbf{2 9}}$ | 2.022821 | 100.2831 |
| $\mathbf{t}_{\mathbf{1 1}}$ | 2.198031 | 108.9693 | $\mathbf{t}_{\mathbf{3 0}}$ | 2.022823 | 100.2832 |
| $\mathbf{t}_{\mathbf{1 2}}$ | 8.126777 | 402.8921 | $\mathbf{t}_{\mathbf{3 1}}$ | 2.022823 | 100.2832 |
| $\mathbf{t}_{\mathbf{1 3}}$ | 2.022821 | 100.2831 | $\mathbf{t}_{\mathbf{3 2}}$ | 2.019175 | 100.1024 |
| $\mathbf{t}_{\mathbf{1 4}}$ | 2.365171 | 117.2554 | $\mathbf{t}_{\mathbf{p}(\mathbf{1})}$ | 2.017145 | 100.0017 |
| $\mathbf{t}_{\mathbf{1 5}}$ | 2.022821 | 100.2831 | $\mathbf{t}_{\mathbf{p}(\mathbf{2})}$ | 2.018095 | 100.0488 |
| $\mathbf{t}_{\mathbf{1 6}}$ | 2.022821 | 100.2831 | $\mathbf{t}_{\mathbf{p}(\mathbf{3})}$ | 2.017808 | 100.0346 |
| $\mathbf{t}_{\mathbf{1 7}}$ | 3.3555886 | 166.3563 | $\mathbf{t}_{\mathbf{p}(\mathbf{4})}$ | 2.017559 | 100.0222 |
| $\mathbf{t}_{\mathbf{1 8}}$ | 5.124432 | 254.0482 | $\mathbf{t}_{\mathbf{p}(\mathbf{5})}$ | 2.017110 | 100.0000 |

### 5.2. SIMULATION STUDY

The computational procedure for comparing estimators is described in this section. For the comparison of the ratio estimators, a bivariate population with a specified correlation between the study and auxiliary variables is required. Srinivas et al. [30] described how to generate such correlated populations using a simple procedure. We have generated two symmetric populations namely Normal, Uniform and two asymmetric populations namely Beta-I, Log-Normal of size $N=10000$ units each using the model $Y=\rho X+\sqrt{1-\rho^{2}} X^{*} ; 0<$ $\rho=0.6,0.7,0.8,0.9<1$ where, X and $\mathrm{X}^{*}$ are independent variates of respective parent distribution.

Table 8. Comparison of ratio estimators of population mean for Simulated Normal Population

| Estimator | $\boldsymbol{\rho}$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | $\mathbf{0 . 6}$ | $\mathbf{0 . 7}$ | $\mathbf{0 . 8}$ | $\mathbf{0 . 9}$ |
| $t_{0}$ | 0.2770852 | 0.2512603 | 0.2213679 | 0.18734630 |
| $t_{1}$ | 0.2224999 | 0.1773046 | 0.1251562 | 0.06605467 |
| $t_{2}$ | 0.3898414 | 0.3106549 | 0.2192858 | 0.11573420 |
| $t_{3}$ | 0.3898414 | 0.3106549 | 0.2192858 | 0.11573420 |
| $t_{4}$ | 0.2224999 | 0.1773046 | 0.1251562 | 0.06605467 |
| $t_{5}$ | 0.2224999 | 0.1773046 | 0.1251562 | 0.06605467 |
| $t_{6}$ | 0.3894628 | 0.3103199 | 0.2190133 | 0.11555090 |
| $t_{7}$ | 0.2301947 | 0.1794773 | 0.1251591 | 0.06998474 |
| $t_{8}$ | 0.3897779 | 0.3105986 | 0.2192400 | 0.11570340 |
| $t_{9}$ | 1.3287470 | 1.1818920 | 0.9785459 | 0.69656600 |
| $t_{10}$ | 0.2769206 | 0.2510703 | 0.2211580 | 0.18712810 |
| $t_{11}$ | 0.3882926 | 0.3089821 | 0.2176353 | 0.11438400 |
| $t_{12}$ | 0.3703253 | 0.2934439 | 0.2053564 | 0.10646920 |
| $t_{13}$ | 0.2224999 | 0.1773046 | 0.1251562 | 0.06605467 |
| $t_{14}$ | 0.3761109 | 0.2960009 | 0.2050618 | 0.10441550 |
| $t_{15}$ | 0.2224999 | 0.1773046 | 0.1251562 | 0.06605467 |
| $t_{16}$ | 0.2224999 | 0.1773046 | 0.1251562 | 0.06605467 |
| $t_{17}$ | 0.3898395 | 0.3106532 | 0.2192844 | 0.11573320 |
| $t_{18}$ | 0.2730589 | 0.2466013 | 0.2162092 | 0.18197140 |
| $t_{19}$ | 0.3898235 | 0.310639 | 0.2192729 | 0.11572550 |
| $t_{20}$ | 0.3898411 | 0.3106546 | 0.2192856 | 0.11573400 |
| $t_{21}$ | 0.2224999 | 0.1773046 | 0.1251562 | 0.06605467 |
| $t_{22}$ | 0.2517396 | 0.2213433 | 0.1876804 | 0.15167180 |
| $t_{23}$ | 0.2748301 | 0.2486541 | 0.2184854 | 0.18434620 |
| $t_{24}$ | 0.2301946 | 0.1794773 | 0.12515910 | 0.06998473 |
| $t_{25}$ | 0.2532104 | 0.2231283 | 0.18973620 | 0.15389510 |
|  |  |  |  |  |
|  |  |  |  |  |


| Estimator | $\boldsymbol{\rho}$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | $\mathbf{0 . 6}$ | $\mathbf{0 . 7}$ | $\mathbf{0 . 8}$ | $\mathbf{0 . 9}$ |
| $t_{26}$ | 0.2224999 | 0.1773046 | 0.12515620 | 0.06605467 |
| $t_{27}$ | 0.2224999 | 0.1773046 | 0.12515620 | 0.06605467 |
| $t_{28}$ | 0.2224999 | 0.1773046 | 0.12515620 | 0.06605467 |
| $t_{29}$ | 0.2224999 | 0.1773046 | 0.12515620 | 0.06605467 |
| $t_{30}$ | 0.2224999 | 0.1773046 | 0.12515620 | 0.06605467 |
| $t_{31}$ | 0.2224999 | 0.1773046 | 0.12515620 | 0.06605467 |
| $t_{32}$ | 0.3898344 | 0.3106499 | 0.21928270 | 0.11573280 |
| $\boldsymbol{t}_{\boldsymbol{p}(\mathbf{1})}$ | $\mathbf{0 . 2 2 2 4 9 8 3}$ | $\mathbf{0 . 1 7 7 3 0 3 3}$ | $\mathbf{0 . 1 2 5 1 5 5 4}$ | $\mathbf{0 . 0 6 6 0 5 4 1 6}$ |
| $\boldsymbol{t}_{\boldsymbol{p}(\mathbf{2})}$ | $\mathbf{0 . 2 2 4 9 8 3}$ | $\mathbf{0 . 1 7 7 3 0 3 4}$ | $\mathbf{0 . 1 2 5 1 5 5 4}$ | $\mathbf{0 . 0 6 6 0 5 4 2 3}$ |
| $\boldsymbol{t}_{\boldsymbol{p}(\mathbf{3})}$ | $\mathbf{0 . 2 2 4 9 8 3}$ | $\mathbf{0 . 1 7 7 3 0 3 3}$ | $\mathbf{0 . 1 2 5 1 5 5 4}$ | $\mathbf{0 . 0 6 6 0 5 4 1 7}$ |
| $\boldsymbol{t}_{\boldsymbol{p}(\mathbf{4})}$ | $\mathbf{0 . 2 2 4 9 8 3}$ | $\mathbf{0 . 1 7 7 3 0 3 3}$ | $\mathbf{0 . 1 2 5 1 5 5 4}$ | $\mathbf{0 . 0 6 6 0 5 4 1 6}$ |
| $\boldsymbol{t}_{\boldsymbol{p}(\mathbf{5})}$ | $\mathbf{0 . 2 2 4 9 8 3}$ | $\mathbf{0 . 1 7 7 3 0 3 3}$ | $\mathbf{0 . 1 2 5 1 5 5 4}$ | $\mathbf{0 . 0 6 6 0 5 4 2 5}$ |

Table 9. PRE for simulated normal population

| Estimator | $\rho$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | 0.6 | 0.7 | 0.8 | 0.9 |
| $t_{0}$ | 124.5336 | 141.7121 | 176.8744 | 283.6249 |
| $t_{1}$ | 100.0007 | 100.0007 | 100.0006 | 100.0006 |
| $t_{2}$ | 175.2110 | 175.2109 | 175.2108 | 175.2108 |
| $t_{3}$ | 175.2110 | 175.2109 | 175.2108 | 175.2108 |
| $t_{4}$ | 100.0007 | 100.0007 | 100.0006 | 100.0006 |
| $t_{5}$ | 100.0007 | 100.0007 | 100.0006 | 100.0006 |
| $t_{6}$ | 175.0408 | 175.0220 | 174.9931 | 174.9333 |
| $t_{7}$ | 103.4591 | 101.2261 | 100.0030 | 105.9504 |
| $t_{8}$ | 175.1824 | 175.1792 | 175.1742 | 175.1642 |
| $t_{9}$ | 597.1942 | 666.5930 | 781.8647 | 1054.536 |
| $t_{10}$ | 124.4596 | 141.6049 | 176.7067 | 283.2946 |
| $t_{11}$ | 174.5149 | 174.2674 | 173.8921 | 173.1668 |
| $t_{12}$ | 166.4396 | 165.5038 | 164.0811 | 161.1845 |
| $t_{13}$ | 100.0007 | 100.0007 | 100.0006 | 100.0006 |
| $t_{14}$ | 169.0399 | 166.9460 | 163.8457 | 158.0754 |
| $t_{15}$ | 100.0007 | 100.0007 | 100.0006 | 100.0006 |
| $t_{16}$ | 100.0007 | 100.0007 | 100.0006 | 100.0006 |
| $t_{17}$ | 175.2101 | 175.2100 | 175.2097 | 175.2093 |
| $t_{18}$ | 122.7240 | 139.0844 | 172.7526 | 275.4878 |
| $t_{19}$ | 175.2029 | 175.2019 | 175.2005 | 175.1977 |
| $t_{20}$ | 175.2108 | 175.2107 | 175.2107 | 175.2105 |
| $t_{21}$ | 100.0007 | 100.0007 | 100.0006 | 100.0006 |
| $t_{22}$ | 113.1423 | 124.8387 | 149.9579 | 229.6170 |
| $t_{23}$ | 123.5201 | 140.2421 | 174.5713 | 279.0830 |
| $t_{24}$ | 103.4590 | 101.2261 | 100.0030 | 105.9504 |
| $t_{25}$ | 113.8033 | 125.8455 | 151.6005 | 232.9829 |
| $t_{26}$ | 100.0007 | 100.0007 | 100.0006 | 100.0006 |
| $t_{27}$ | 100.0007 | 100.0007 | 100.0006 | 100.0006 |
| $t_{28}$ | 100.0007 | 100.0007 | 100.0006 | 100.0006 |
| $t_{29}$ | 100.0007 | 100.0007 | 100.0006 | 100.0006 |
| $t_{30}$ | 100.0007 | 100.0007 | 100.0006 | 100.0006 |
| $t_{31}$ | 100.0007 | 100.0007 | 100.0006 | 100.0006 |
| $t_{32}$ | 175.2078 | 175.2081 | 175.2083 | 175.2087 |
| $\boldsymbol{t}_{\boldsymbol{p}(\mathbf{1})}$ | 100.0000 | 100.0000 | 100.0000 | 99.99986 |
| $\boldsymbol{t}_{\boldsymbol{p}(2)}$ | 100.0000 | 100.0001 | 100.0000 | 99.99997 |
| $\boldsymbol{t}_{\boldsymbol{p}(3)}$ | 100.0000 | 100.0000 | 100.0000 | 99.99988 |
| $t_{p(4)}$ | 100.0000 | 100.0000 | 100.0000 | 99.99986 |
| $\boldsymbol{t}_{\boldsymbol{p}(5)}$ | 100.0000 | 100.0000 | 100.0000 | 100.0000 |

Table 10. Comparison of ratio estimators of population mean for Simulated Uniform Population

| Estimator | $\rho$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | 0.6 | 0.7 | 0.8 | 0.9 |
| $t_{0}$ | 0.001518244 | 0.0014473490 | 0.001367226 | 0.0012789710 |
| $t_{1}$ | 0.001107771 | 0.0008827548 | 0.000623121 | 0.0003288694 |
| $t_{2}$ | 0.002227942 | 0.0017753910 | 0.001253217 | 0.0006614203 |
| $t_{3}$ | 0.002227942 | 0.0017753910 | 0.001253217 | 0.0006614203 |
| $t_{4}$ | 0.001107771 | 0.0008827548 | 0.000623121 | 0.0003288694 |
| $t_{5}$ | 0.001107771 | 0.0008827548 | 0.000623121 | 0.0003288694 |
| $t_{6}$ | 0.002139741 | 0.0016969800 | 0.001189124 | 0.0006181472 |
| $t_{7}$ | 0.001151389 | 0.0008921056 | 0.000624305 | 0.0003684822 |
| $t_{8}$ | 0.002208848 | 0.0017583840 | 0.001239274 | 0.0006519483 |
| $t_{9}$ | 0.008711274 | 0.0078575500 | 0.006626538 | 0.0048575770 |
| $t_{10}$ | 0.001517651 | 0.0014466540 | 0.001366447 | 0.0012781470 |
| $t_{11}$ | 0.002007332 | 0.0015464350 | 0.001040107 | 0.0005028236 |
| $t_{12}$ | 0.001265527 | 0.0009638183 | 0.000645379 | 0.0003296018 |
| $t_{13}$ | 0.001107771 | 0.0008827548 | 0.000623121 | 0.0003288694 |
| $t_{14}$ | 0.001479850 | 0.0010712900 | 0.000678485 | 0.0003288721 |
| $t_{15}$ | 0.001107771 | 0.0008827548 | 0.000623121 | 0.0003288694 |
| $t_{16}$ | 0.001107771 | 0.0008827548 | 0.000623121 | 0.0003288694 |
| $t_{17}$ | 0.002227889 | 0.0017753440 | 0.001253178 | 0.0006613937 |
| $t_{18}$ | 0.001517863 | 0.0014469020 | 0.001366725 | 0.0012784410 |
| $t_{19}$ | 0.002227665 | 0.0017751440 | 0.001253015 | 0.0006612825 |
| $t_{20}$ | 0.002227931 | 0.0017753810 | 0.001253209 | 0.0006614147 |
| $t_{21}$ | 0.001107771 | 0.0008827548 | 0.000623121 | 0.0003288694 |
| $t_{22}$ | 0.001497661 | 0.0014232040 | 0.001340113 | 0.0012502300 |
| $t_{23}$ | 0.001518222 | 0.0014473220 | 0.001367196 | 0.0012789390 |
| $t_{24}$ | 0.001151389 | 0.0008921056 | 0.000624305 | 0.0003684822 |
| $t_{25}$ | 0.001507461 | 0.0014347110 | 0.001353045 | 0.0012639510 |
| $t_{26}$ | 0.001107771 | 0.0008827548 | 0.000623121 | 0.0003288694 |
| $t_{27}$ | 0.001107771 | 0.0008827548 | 0.000623121 | 0.0003288694 |
| $t_{28}$ | 0.001107771 | 0.0008827548 | 0.000623121 | 0.0003288694 |
| $t_{29}$ | 0.001107771 | 0.0008827548 | 0.000623121 | 0.0003288694 |
| $t_{30}$ | 0.001107771 | 0.0008827548 | 0.000623121 | 0.0003288694 |
| $t_{31}$ | 0.001107771 | 0.0008827548 | 0.000623121 | 0.0003288694 |
| $t_{32}$ | 0.001107762 | 0.0008827491 | 0.001251787 | 0.0003288685 |
| $\boldsymbol{t}_{\boldsymbol{p}(1)}$ | 0.001107747 | 0.0008827365 | 0.000623107 | 0.0003288631 |
| $t_{p(2)}$ | 0.001107767 | 0.0008827543 | 0.000623120 | 0.0003288665 |
| $t_{p(3)}$ | 0.001107766 | 0.0008827541 | 0.000623121 | 0.0003288672 |
| $\boldsymbol{t}_{\boldsymbol{p}(4)}$ | 0.00110776 | 0.0008827503 | 0.000623120 | 0.0003288694 |
| $\boldsymbol{t}_{\boldsymbol{p}(5)}$ | 0.001107747 | 0.0008827362 | 0.000623107 | 0.0003288625 |

Table 11. PRE for simulated uniform population

| Estimator | $\boldsymbol{\rho}$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | $\mathbf{0 . 6}$ | $\mathbf{0 . 7}$ | $\mathbf{0 . 8}$ | $\mathbf{0 . 9}$ |
| $t_{0}$ | 137.0569 | 163.9617 | 219.4207 | 388.9075 |
| $t_{1}$ | 100.0022 | 100.0021 | 100.0022 | 100.0021 |
| $t_{2}$ | 201.1237 | 201.1236 | 201.1239 | 201.1237 |
| $t_{3}$ | 201.1237 | 201.1236 | 201.1239 | 201.1237 |
| $t_{4}$ | 100.0022 | 100.0021 | 100.0022 | 100.0021 |
| $t_{5}$ | 100.0022 | 100.0021 | 100.0022 | 100.0021 |
| $t_{6}$ | 193.1615 | 192.2409 | 190.8378 | 187.9652 |
| $t_{7}$ | 103.9397 | 101.0614 | 100.1923 | 112.0475 |
| $t_{8}$ | 199.4000 | 199.1970 | 198.8862 | 198.2434 |
| $t_{9}$ | 786.3956 | 890.1357 | 1063.467 | 1477.084 |
| $t_{10}$ | 137.0034 | 163.8829 | 219.2957 | 388.6570 |
| $t_{11}$ | 181.2085 | 175.1865 | 166.9227 | 152.8978 |
| $t_{12}$ | 114.2433 | 109.1853 | 103.5743 | 100.2248 |


| Estimator | $\boldsymbol{\rho}$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | $\mathbf{0 . 6}$ | $\mathbf{0 . 7}$ | $\mathbf{0 . 8}$ | $\mathbf{0 . 9}$ |
| $t_{13}$ | 100.0022 | 100.0021 | 100.0022 | 100.0021 |
| $t_{14}$ | 133.5910 | 121.3602 | 108.8874 | 100.0029 |
| $t_{15}$ | 100.0022 | 100.0021 | 100.0022 | 100.0021 |
| $t_{16}$ | 100.0022 | 100.0021 | 100.0022 | 100.0021 |
| $t_{17}$ | 201.1189 | 201.1183 | 201.1176 | 201.1156 |
| $t_{18}$ | 137.0225 | 163.9110 | 219.3403 | 388.7464 |
| $t_{19}$ | 201.0987 | 201.0956 | 201.0915 | 201.0818 |
| $t_{20}$ | 201.1227 | 201.1225 | 201.1226 | 201.1220 |
| $t_{21}$ | 100.0022 | 100.0021 | 100.0022 | 100.0021 |
| $t_{22}$ | 135.1988 | 161.2264 | 215.0695 | 380.1680 |
| $t_{23}$ | 137.0549 | 163.9586 | 219.4159 | 388.8978 |
| $t_{24}$ | 103.9397 | 101.0614 | 100.1923 | 112.0475 |
| $t_{25}$ | 136.0835 | 162.5300 | 217.1449 | 384.3403 |
| $t_{26}$ | 100.0022 | 100.0021 | 100.0022 | 100.0021 |
| $t_{27}$ | 100.0022 | 100.0021 | 100.0022 | 100.0021 |
| $t_{28}$ | 100.0022 | 100.0021 | 100.0022 | 100.0021 |
| $t_{29}$ | 100.0022 | 100.0021 | 100.0022 | 100.0021 |
| $t_{30}$ | 100.0022 | 100.0021 | 100.0022 | 100.0021 |
| $t_{31}$ | 100.0022 | 100.0021 | 100.0022 | 100.0021 |
| $t_{32}$ | 100.0014 | 100.0015 | 200.8944 | 100.0018 |
| $\boldsymbol{t}_{\boldsymbol{p}(\mathbf{1})}$ | $\mathbf{1 0 0 . 0 0 0 0}$ | $\mathbf{1 0 0 . 0 0 0 0}$ | $\mathbf{1 0 0 . 0 0 0 0}$ | $\mathbf{1 0 0 . 0 0 0 2}$ |
| $\boldsymbol{t}_{\boldsymbol{p} \mathbf{( 2 )}}$ | $\mathbf{1 0 0 . 0 0 1 8}$ | $\mathbf{1 0 0 . 0 0 2 1}$ | $\mathbf{1 0 0 . 0 0 2 1}$ | $\mathbf{1 0 0 . 0 0 1 2}$ |
| $\boldsymbol{t}_{\boldsymbol{p}(\mathbf{3})}$ | $\mathbf{1 0 0 . 0 0 1 7}$ | $\mathbf{1 0 0 . 0 0 2}$ | $\mathbf{1 0 0 . 0 0 2 2}$ | $\mathbf{1 0 0 . 0 0 1 4}$ |
| $\boldsymbol{t}_{\boldsymbol{p}(\mathbf{4})}$ | $\mathbf{1 0 0 . 0 0 1 2}$ | $\mathbf{1 0 0 . 0 0 1 6}$ | $\mathbf{1 0 0 . 0 0 2 1}$ | $\mathbf{1 0 0 . 0 0 2 1}$ |
| $\boldsymbol{p}_{\boldsymbol{p}(\mathbf{5})}$ | $\mathbf{1 0 0 . 0 0 0 0}$ | $\mathbf{1 0 0 . 0 0 0}$ | $\mathbf{1 0 0 . 0 0 0 0}$ | $\mathbf{1 0 0 . 0 0 0 0}$ |

Table 12. Comparison of ratio estimators of population mean for simulated Log-normal population

| Estimator | $\boldsymbol{\rho}$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | $\mathbf{0 . 6}$ | $\mathbf{0 . 7}$ | $\mathbf{0 . 8}$ | $\mathbf{0 . 9}$ |
| $t_{0}$ | 0.0001657873 | 0.0001743760 | 0.0001844353 | 0.0001960627 |
| $t_{1}$ | $9.181981 \mathrm{e}-05$ | $7.316891 \mathrm{e}-05$ | $5.164864 \mathrm{e}-05$ | $2.725901 \mathrm{e}-05$ |
| $t_{2}$ | 0.0002433058 | 0.0001938843 | 0.0001368595 | $7.223140 \mathrm{e}-05$ |
| $t_{3}$ | 0.0002433058 | 0.0001938843 | 0.0001368595 | $7.223140 \mathrm{e}-05$ |
| $t_{4}$ | $9.181981 \mathrm{e}-05$ | $7.316891 \mathrm{e}-05$ | $5.164864 \mathrm{e}-05$ | $2.725901 \mathrm{e}-05$ |
| $t_{5}$ | $9.181981 \mathrm{e}-05$ | $7.316891 \mathrm{e}-05$ | $5.164864 \mathrm{e}-05$ | $2.725901 \mathrm{e}-05$ |
| $t_{6}$ | 0.000122758 | $9.077962 \mathrm{e}-05$ | $5.807458 \mathrm{e}-05$ | $2.738201 \mathrm{e}-05$ |
| $t_{7}$ | $9.525625 \mathrm{e}-05$ | $7.338368 \mathrm{e}-05$ | $5.296234 \mathrm{e}-05$ | $3.713840 \mathrm{e}-05$ |
| $t_{8}$ | 0.0002240488 | 0.0001766549 | 0.0001226808 | $6.259102 \mathrm{e}-05$ |
| $t_{9}$ | 0.0011951460 | 0.0010993640 | 0.0009507640 | 0.0007244692 |
| $t_{10}$ | $9.879226 \mathrm{e}-05$ | $7.474506 \mathrm{e}-05$ | $5.178201 \mathrm{e}-05$ | $3.302812 \mathrm{e}-05$ |
| $t_{11}$ | 0.0001124595 | $7.949035 \mathrm{e}-05$ | $5.17596 \mathrm{e}-05$ | $3.198116 \mathrm{e}-05$ |
| $t_{12}$ | 0.000137751 | 0.0001408177 | 0.000146002 | 0.0001543792 |
| $t_{13}$ | $9.181981 \mathrm{e}-05$ | $7.316891 \mathrm{e}-05$ | $5.164864 \mathrm{e}-05$ | $2.725901 \mathrm{e}-05$ |
| $t_{14}$ | $9.369701 \mathrm{e}-05$ | $7.367427 \mathrm{e}-05$ | $5.978484 \mathrm{e}-05$ | $5.417107 \mathrm{e}-05$ |
| $t_{15}$ | $9.181981 \mathrm{e}-05$ | $7.316891 \mathrm{e}-05$ | $5.164864 \mathrm{e}-05$ | $2.725901 \mathrm{e}-05$ |
| $t_{16}$ | $9.181981 \mathrm{e}-05$ | $7.316891 \mathrm{e}-05$ | $5.164864 \mathrm{e}-05$ | $2.725901 \mathrm{e}-05$ |
| $t_{17}$ | 0.0001014359 | $9.363731 \mathrm{e}-05$ | $8.842545 \mathrm{e}-05$ | $8.827385 \mathrm{e}-05$ |
| $t_{18}$ | 0.0001058297 | $9.990263 \mathrm{e}-05$ | $9.656087 \mathrm{e}-05$ | $9.808899 \mathrm{e}-05$ |
| $t_{19}$ | 0.0001191694 | 0.0001176183 | 0.0001185185 | $3.587589 \mathrm{e}-05$ |
| $t_{20}$ | 0.0001608043 | 0.0001215856 | $7.92973 \mathrm{e}-05$ | $3.587589 \mathrm{e}-05$ |
| $t_{21}$ | $9.181981 \mathrm{e}-05$ | $7.316891 \mathrm{e}-05$ | $5.164864 \mathrm{e}-05$ | $2.725901 \mathrm{e}-05$ |
| $t_{22}$ | 0.0001175534 | 0.0001155379 | 0.0001159964 | 0.0001207477 |
| $t_{23}$ | 0.0001033459 | $9.640315 \mathrm{e}-05$ | $9.205067 \mathrm{e}-05$ | $9.267838 \mathrm{e}-05$ |
| $t_{24}$ | $9.525625 \mathrm{e}-05$ | $7.338369 \mathrm{e}-05$ | $5.296235 \mathrm{e}-05$ | $3.713840 \mathrm{e}-05$ |
| $t_{25}$ | 0.0001655167 | 0.0001740573 | 0.0001840752 | 0.0001956773 |
| $t_{26}$ | $9.181981 \mathrm{e}-05$ | $7.316891 \mathrm{e}-05$ | $5.164864 \mathrm{e}-05$ | $2.725901 \mathrm{e}-05$ |


| Estimator | $\rho$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | 0.6 | 0.7 | 0.8 | 0.9 |
| $t_{27}$ | 9.181981e-05 | 7.316891e-05 | 5.164864e-05 | $2.725901 \mathrm{e}-05$ |
| $t_{28}$ | 9.181981e-05 | $7.316891 \mathrm{e}-05$ | $5.164864 \mathrm{e}-05$ | $2.725901 \mathrm{e}-05$ |
| $t_{29}$ | 9.181981e-05 | 7.316891e-05 | $5.164864 \mathrm{e}-05$ | $2.725901 \mathrm{e}-05$ |
| $t_{30}$ | 9.181981e-05 | $7.316891 \mathrm{e}-05$ | $5.164864 \mathrm{e}-05$ | $2.725901 \mathrm{e}-05$ |
| $t_{31}$ | 9.181981e-05 | $7.316891 \mathrm{e}-05$ | $5.164864 \mathrm{e}-05$ | $2.725901 \mathrm{e}-05$ |
| $t_{32}$ | 0.0002300046 | 0.0001804162 | 0.000120841 | $6.047715 \mathrm{e}-05$ |
| $\boldsymbol{t}_{\boldsymbol{p}(1)}$ | 9.180510e-05 | 7.315633e-05 | 5.163917e-05 | $2.725344 \mathrm{e}-05$ |
| $t_{p(2)}$ | $9.180901 \mathrm{e}-05$ | $7.316089 \mathrm{e}-05$ | $5.164389 \mathrm{e}-05$ | 2.725736e-05 |
| $\boldsymbol{t}_{\boldsymbol{p}(3)}$ | 9.180744e-05 | 7.315913e-05 | 5.164215e-05 | $2.725606 \mathrm{e}-05$ |
| $\boldsymbol{t}_{\boldsymbol{p}(4)}$ | $9.180567 \mathrm{e}-05$ | 7.315714e-05 | $5.164019 \mathrm{e}-05$ | $2.725454 \mathrm{e}-05$ |
| $t_{p(5)}$ | $9.180605 \mathrm{e}-05$ | 7.315717e-05 | 5.164034e-05 | 2.725429e-05 |

Table 13. PRE for simulated Log-normal population

| Estimator | $\rho$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | 0.6 | 0.7 | 0.8 | 0.9 |
| $t_{0}$ | 180.5843 | 238.358 | 357.1535 | 719.3829 |
| $t_{1}$ | 100.0150 | 100.016 | 100.0161 | 100.0173 |
| $t_{2}$ | 265.0215 | 265.0243 | 265.0244 | 265.0276 |
| $t_{3}$ | 265.0215 | 265.0243 | 265.0244 | 265.0276 |
| $t_{4}$ | 100.0150 | 100.0160 | 100.0161 | 100.0173 |
| $t_{5}$ | 100.0150 | 100.0160 | 100.0161 | 100.0173 |
| $t_{6}$ | 133.7145 | 124.0885 | 112.4597 | 100.4686 |
| $t_{7}$ | 103.7581 | 100.3096 | 102.5600 | 136.2663 |
| $t_{8}$ | 244.0458 | 241.4731 | 237.5678 | 229.6557 |
| $t_{9}$ | 1301.816 | 1502.743 | 1841.127 | 2658.184 |
| $t_{10}$ | 107.6097 | 102.1705 | 100.2743 | 121.1850 |
| $t_{11}$ | 122.4968 | 108.6570 | 100.2309 | 117.3436 |
| $t_{12}$ | 150.0457 | 192.4865 | 282.7286 | 566.4400 |
| $t_{13}$ | 100.0150 | 100.0160 | 100.0161 | 100.0173 |
| $t_{14}$ | 102.0597 | 100.7068 | 115.7716 | 198.7616 |
| $t_{15}$ | 100.0150 | 100.0160 | 100.0161 | 100.0173 |
| $t_{16}$ | 100.0150 | 100.0160 | 100.0161 | 100.0173 |
| $t_{17}$ | 110.4893 | 127.9947 | 171.2333 | 323.8897 |
| $t_{18}$ | 115.2753 | 136.5589 | 186.9873 | 359.9029 |
| $t_{19}$ | 129.8056 | 160.7748 | 229.5076 | 131.6339 |
| $t_{20}$ | 175.1565 | 166.1978 | 153.5569 | 131.6339 |
| $t_{21}$ | 100.0150 | 100.0160 | 100.0161 | 100.0173 |
| $t_{22}$ | 128.0454 | 157.9311 | 224.6236 | 443.0411 |
| $t_{23}$ | 112.5698 | 131.7754 | 178.2534 | 340.0506 |
| $t_{24}$ | 103.7581 | 100.3096 | 102.5600 | 136.2663 |
| $t_{25}$ | 180.2895 | 237.9224 | 356.4562 | 717.9688 |
| $t_{26}$ | 100.0150 | 100.0160 | 100.01610 | 100.0173 |
| $t_{27}$ | 100.0150 | 100.0160 | 100.01610 | 100.0173 |
| $t_{28}$ | 100.0150 | 100.0160 | 100.01610 | 100.0173 |
| $t_{29}$ | 100.0150 | 100.0160 | 100.01610 | 100.0173 |
| $t_{30}$ | 100.0150 | 100.0160 | 100.01610 | 100.0173 |
| $t_{31}$ | 100.0150 | 100.0160 | 100.01610 | 100.0173 |
| $t_{32}$ | 250.5332 | 246.6145 | 234.0050 | 221.8996 |
| $\boldsymbol{t}_{\boldsymbol{p}(1)}$ | 99.99897 | 99.99885 | 99.99773 | 99.99688 |
| $\boldsymbol{t}_{\boldsymbol{p}(2)}$ | 100.0032 | 100.0051 | 100.0069 | 100.0113 |
| $\boldsymbol{t}_{\boldsymbol{p}(3)}$ | 100.0015 | 100.0027 | 100.0035 | 100.0065 |
| $\boldsymbol{t}_{\boldsymbol{p}(4)}$ | 99.99959 | 99.99996 | 99.99971 | 100.0009 |
| $t_{p(5)}$ | 100.0000 | 100.0000 | 100.0000 | 100.0000 |

Table 14. Comparison of ratio estimators of population mean for simulated Beta population
Estimator

|  | 0.6 | 0.7 | 0.8 | 0.9 |
| :---: | :---: | :---: | :---: | :---: |
| $t_{0}$ | $1.600922 \mathrm{e}-05$ | $1.525086 \mathrm{e}-05$ | $1.438764 \mathrm{e}-05$ | $1.342725 \mathrm{e}-05$ |
| $t_{1}$ | $1.166382 \mathrm{e}-05$ | $9.294609 \mathrm{e}-06$ | $6.560901 \mathrm{e}-06$ | $3.462698 \mathrm{e}-06$ |
| $t_{2}$ | $2.170868 \mathrm{e}-05$ | 1.72991e-05 | $1.221113 \mathrm{e}-05$ | 6.444764e-06 |
| $t_{3}$ | $2.170868 \mathrm{e}-05$ | 1.72991e-05 | 1.221113e-05 | $6.444764 \mathrm{e}-06$ |
| $t_{4}$ | $1.166382 \mathrm{e}-05$ | $9.294609 \mathrm{e}-06$ | 6.560901e-06 | $3.462698 \mathrm{e}-06$ |
| $t_{5}$ | $1.166382 \mathrm{e}-05$ | $9.294609 \mathrm{e}-06$ | $6.560901 \mathrm{e}-06$ | $3.462698 \mathrm{e}-06$ |
| $t_{6}$ | $1.437119 \mathrm{e}-05$ | $1.098636 \mathrm{e}-05$ | $7.328383 \mathrm{e}-06$ | $3.559013 \mathrm{e}-06$ |
| $t_{7}$ | $1.195802 \mathrm{e}-05$ | $9.332376 \mathrm{e}-06$ | $6.605128 \mathrm{e}-06$ | $3.97378 \mathrm{e}-06$ |
| $t_{8}$ | $1.958308 \mathrm{e}-05$ | $1.540988 \mathrm{e}-05$ | $1.067019 \mathrm{e}-05$ | $5.413374 \mathrm{e}-06$ |
| $t_{9}$ | $8.261556 \mathrm{e}-05$ | $7.488819 \mathrm{e}-05$ | $6.358867 \mathrm{e}-05$ | $4.716008 \mathrm{e}-05$ |
| $t_{10}$ | $1.576126 \mathrm{e}-05$ | $1.495907 \mathrm{e}-05$ | $1.40586 \mathrm{e}-05$ | $1.307625 \mathrm{e}-05$ |
| $t_{11}$ | $1.219994 \mathrm{e}-05$ | $9.315742 \mathrm{e}-06$ | $6.783533 \mathrm{e}-06$ | $4.779543 \mathrm{e}-06$ |
| $t_{12}$ | $1.415159 \mathrm{e}-05$ | $1.302615 \mathrm{e}-05$ | $1.184165 \mathrm{e}-05$ | $1.067265 \mathrm{e}-05$ |
| $t_{13}$ | $1.166382 \mathrm{e}-05$ | $9.294609 \mathrm{e}-06$ | 6.560901e-06 | $3.462698 \mathrm{e}-06$ |
| $t_{14}$ | $1.251283 \mathrm{e}-05$ | $1.13417 \mathrm{e}-05$ | $1.029412 \mathrm{e}-05$ | $9.416891 \mathrm{e}-06$ |
| $t_{15}$ | $1.166382 \mathrm{e}-05$ | $9.294609 \mathrm{e}-06$ | $6.560901 \mathrm{e}-06$ | $3.462698 \mathrm{e}-06$ |
| $t_{16}$ | $1.166382 \mathrm{e}-05$ | $9.294609 \mathrm{e}-06$ | 6.560901e-06 | $3.462698 \mathrm{e}-06$ |
| $t_{17}$ | $1.893917 \mathrm{e}-05$ | $1.484403 \mathrm{e}-05$ | $1.02169 \mathrm{e}-05$ | $5.121822 \mathrm{e}-06$ |
| $t_{18}$ | $1.587204 \mathrm{e}-05$ | $1.508958 \mathrm{e}-05$ | 1.420592e-05 | $1.323356 \mathrm{e}-05$ |
| $t_{19}$ | $1.443537 \mathrm{e}-05$ | $1.103732 \mathrm{e}-05$ | $7.362204 \mathrm{e}-06$ | $3.570523 \mathrm{e}-06$ |
| $t_{20}$ | $2.114336 \mathrm{e}-05$ | $1.679384 \mathrm{e}-05$ | $1.179543 \mathrm{e}-05$ | $6.161383 \mathrm{e}-06$ |
| $t_{21}$ | $1.166382 \mathrm{e}-05$ | $9.294609 \mathrm{e}-06$ | 6.560901e-06 | $3.462698 \mathrm{e}-06$ |
| $t_{22}$ | $1.598764 \mathrm{e}-05$ | $1.522551 \mathrm{e}-05$ | $1.43591 \mathrm{e}-05$ | $1.339685 \mathrm{e}-05$ |
| $t_{23}$ | $1.599946 \mathrm{e}-05$ | $1.52394 \mathrm{e}-05$ | $1.437473 \mathrm{e}-05$ | $1.34135 \mathrm{e}-05$ |
| $t_{24}$ | $1.195802 \mathrm{e}-05$ | $9.332377 \mathrm{e}-06$ | $6.605129 \mathrm{e}-06$ | $3.97378 \mathrm{e}-06$ |
| $t_{25}$ | $1.600043 \mathrm{e}-05$ | $1.524055 \mathrm{e}-05$ | 1.437602e-05 | $1.341488 \mathrm{e}-05$ |
| $t_{26}$ | $1.166382 \mathrm{e}-05$ | $9.294609 \mathrm{e}-06$ | $6.560901 \mathrm{e}-06$ | $3.462698 \mathrm{e}-06$ |
| $t_{27}$ | $1.166382 \mathrm{e}-05$ | $9.294609 \mathrm{e}-06$ | $6.560901 \mathrm{e}-06$ | $3.462698 \mathrm{e}-06$ |
| $t_{28}$ | $1.166382 \mathrm{e}-05$ | $9.294609 \mathrm{e}-06$ | $6.560901 \mathrm{e}-06$ | $3.462698 \mathrm{e}-06$ |
| $t_{29}$ | $1.166382 \mathrm{e}-05$ | $9.294609 \mathrm{e}-06$ | $6.560901 \mathrm{e}-06$ | $3.462698 \mathrm{e}-06$ |
| $t_{30}$ | $1.166382 \mathrm{e}-05$ | $9.294609 \mathrm{e}-06$ | $6.560901 \mathrm{e}-06$ | $3.462698 \mathrm{e}-06$ |
| $t_{31}$ | $1.166382 \mathrm{e}-05$ | $9.294609 \mathrm{e}-06$ | $6.560901 \mathrm{e}-06$ | $3.462698 \mathrm{e}-06$ |
| $t_{32}$ | $1.985868 \mathrm{e}-05$ | $1.536875 \mathrm{e}-05$ | $1.040142 \mathrm{e}-05$ | $5.083501 \mathrm{e}-06$ |
| $\boldsymbol{t}_{\boldsymbol{p}(1)}$ | 1.166341e-05 | $9.294285 \mathrm{e}-06$ | 6.560770e-06 | 3.462583e-06 |
| $\boldsymbol{t}_{\boldsymbol{p}(2)}$ | $1.166375 \mathrm{e}-05$ | $9.294592 \mathrm{e}-06$ | $6.560900 \mathrm{e}-06$ | 3.462644e-06 |
| $t_{p(3)}$ | $1.166372 \mathrm{e}-05$ | 9.294579e-06 | 6.560901e-06 | $3.462661 \mathrm{e}-06$ |
| $t_{p(4)}$ | $1.166357 \mathrm{e}-05$ | $9.294474 \mathrm{e}-06$ | 6.560860e-06 | $3.462697 \mathrm{e}-06$ |
| $\boldsymbol{t}_{\boldsymbol{p}(5)}$ | $1.166344 \mathrm{e}-05$ | $9.29432 \mathrm{e}-06$ | $\mathbf{6 . 5 6 0 7 1 5 e - 0 6}$ | 3.462617e-06 |

Table 15. PRE for simulated Beta population

| Estimator | $\boldsymbol{\rho}$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | $\mathbf{0 . 6}$ | $\mathbf{0 . 7}$ | $\mathbf{0 . 8}$ | $\mathbf{0 . 9}$ |
| $t_{0}$ | 137.2598 | 164.0880 | 219.2999 | 387.7775 |
| $t_{1}$ | 100.0033 | 100.0031 | 100.0028 | 100.0023 |
| $t_{2}$ | 186.1259 | 186.1255 | 186.1250 | 186.1241 |
| $t_{3}$ | 186.1259 | 186.1255 | 186.1250 | 186.1241 |
| $t_{4}$ | 100.0033 | 100.0031 | 100.0028 | 100.0023 |
| $t_{5}$ | 100.0033 | 100.0031 | 100.0028 | 100.0023 |
| $t_{6}$ | 123.2157 | 118.2051 | 111.7010 | 102.7839 |
| $t_{7}$ | 102.5257 | 100.4095 | 100.6770 | 114.7623 |
| $t_{8}$ | 167.9014 | 165.7989 | 162.6376 | 156.3376 |
| $t_{9}$ | 708.3293 | 805.7415 | 969.2338 | 1361.978 |
| $t_{10}$ | 135.1339 | 160.9485 | 214.2846 | 377.6407 |
| $t_{11}$ | 104.5998 | 100.2305 | 103.3962 | 138.0327 |
| $t_{12}$ | 121.3329 | 140.1517 | 180.4933 | 308.2250 |
| $t_{13}$ | 100.0033 | 100.0031 | 100.0028 | 100.0023 |
| $t_{14}$ | 107.2825 | 122.0283 | 156.9055 | 271.9588 |


| Estimator | $\boldsymbol{\rho}$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | $\mathbf{0 . 6}$ | $\mathbf{0 . 7}$ | $\mathbf{0 . 8}$ | $\mathbf{0 . 9}$ |
| $t_{15}$ | 100.0033 | 100.0031 | 100.0028 | 100.0023 |
| $t_{16}$ | 100.0033 | 100.0031 | 100.0028 | 100.0023 |
| $t_{17}$ | 162.3807 | 159.7108 | 155.7285 | 147.9177 |
| $t_{18}$ | 136.0837 | 162.3527 | 216.5301 | 382.1838 |
| $t_{19}$ | 123.7660 | 118.7534 | 112.2165 | 103.1163 |
| $t_{20}$ | 181.2789 | 180.6893 | 179.7888 | 177.9401 |
| $t_{21}$ | 100.0033 | 100.0031 | 100.0028 | 100.0023 |
| $t_{22}$ | 137.0748 | 163.8152 | 218.8649 | 386.8996 |
| $t_{23}$ | 137.1762 | 163.9647 | 219.1031 | 387.3804 |
| $t_{24}$ | 102.5257 | 100.4095 | 100.6770 | 114.7623 |
| $t_{25}$ | 137.1845 | 163.9770 | 219.1228 | 387.4203 |
| $t_{26}$ | 100.0033 | 100.0031 | 100.0028 | 100.0023 |
| $t_{27}$ | 100.0033 | 100.0031 | 100.0028 | 100.0023 |
| $t_{28}$ | 100.0033 | 100.0031 | 100.0028 | 100.0023 |
| $t_{29}$ | 100.0033 | 100.0031 | 100.0028 | 100.0023 |
| $t_{30}$ | 100.0033 | 100.0031 | 100.0028 | 100.0023 |
| $t_{31}$ | 100.0033 | 100.0031 | 100.0028 | 100.0023 |
| $t_{32}$ | 170.2643 | 165.3564 | 158.5410 | 146.8110 |
| $\boldsymbol{p}_{\boldsymbol{p}(\mathbf{1})}$ | $\mathbf{9 9 . 9 9 9 7 4}$ | $\mathbf{9 9 . 9 9 9 6 2}$ | $\mathbf{1 0 0 . 0 0 0 8}$ | $\mathbf{9 9 . 9 9 9 0 2}$ |
| $\boldsymbol{t}_{\boldsymbol{p}(\mathbf{2})}$ | $\mathbf{1 0 0 . 0 0 2 7}$ | $\mathbf{1 0 0 . 0 0 2 9}$ | $\mathbf{1 0 0 . 0 0 2 8}$ | $\mathbf{1 0 0 . 0 0 0 8}$ |
| $\boldsymbol{t}_{\boldsymbol{p}(\mathbf{3})}$ | $\mathbf{1 0 0 . 0 0 2 4}$ | $\mathbf{1 0 0 . 0 0 2 8}$ | $\mathbf{1 0 0 . 0 0 2 8}$ | $\mathbf{1 0 0 . 0 0 1 3}$ |
| $\boldsymbol{t}_{\boldsymbol{p}(\mathbf{4})}$ | $\mathbf{1 0 0 . 0 0 1 1}$ | $\mathbf{1 0 0 . 0 0 1 7}$ | $\mathbf{1 0 0 . 0 0 2 2}$ | $\mathbf{1 0 0 . 0 0 2 3}$ |
| $\boldsymbol{t}_{\boldsymbol{p}(\mathbf{5})}$ | $\mathbf{1 0 0 . 0 0 0 0}$ | $\mathbf{1 0 0 . 0 0 0 0}$ | $\mathbf{1 0 0 . 0 0 0 0}$ | $\mathbf{1 0 0 . 0 0 0 0}$ |

## 6. RESULTS AND DISCUSSION

Table 3 lists the conditions in which our proposed class of estimators surpasses the existing ones. Tables 4 and 6 contains the parametric values of two real data that we used to empirically validate our results. Tables 5 and 7 contains the MSE and PRE of the existing and proposed estimator for the two populations respectively. Tables $8,10,12$, and14 contains the MSE of simulated population of Normal, Uniform, Log-normal and Beta respectively. Tables 9, 11, 13, and 15 consist PRE of the simulated population of Normal, Uniform, Log-normal and Beta respectively. We examine the proposed class's Bias and MSE up to first order of approximation. Since Efficiency is stronger property than the unbiasedness hence as a result, we prefer the biased estimator with the lowest MSE over the unbiased estimator with a higher MSE in this case. We can easily notice that the suggested class of estimators has lower MSE and PRE, demonstrating that our proposed class of estimators is efficient enough for practical purposes.

## 7. CONCLUSIONS

In this manuscript, we have suggested a generalized class of estimators of population mean using known auxiliary parameters. We studied the biases and MSEs of the suggested class up to the first order of approximation. We compared the suggested family with the competing estimators of population mean and the efficiency conditions over competing estimators are obtained. These efficiency conditions are verified using both real and simulated data sets. From the results, it is observed that the suggested estimator is the best among the competing estimators. Hence, we can undoubtedly recommend the proposed class of estimator for practical utility in different fields like agriculture, medical sciences, economics,
commerce, engineering etc. In the light of above results and observations, the suggested estimator is recommended for practical applications in different areas of applications.

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